

CS 4803 / 7643: Deep Learning

Topics:

- Convolutional Neural Networks
 - What is a convolution?
 - FC vs Conv Layers

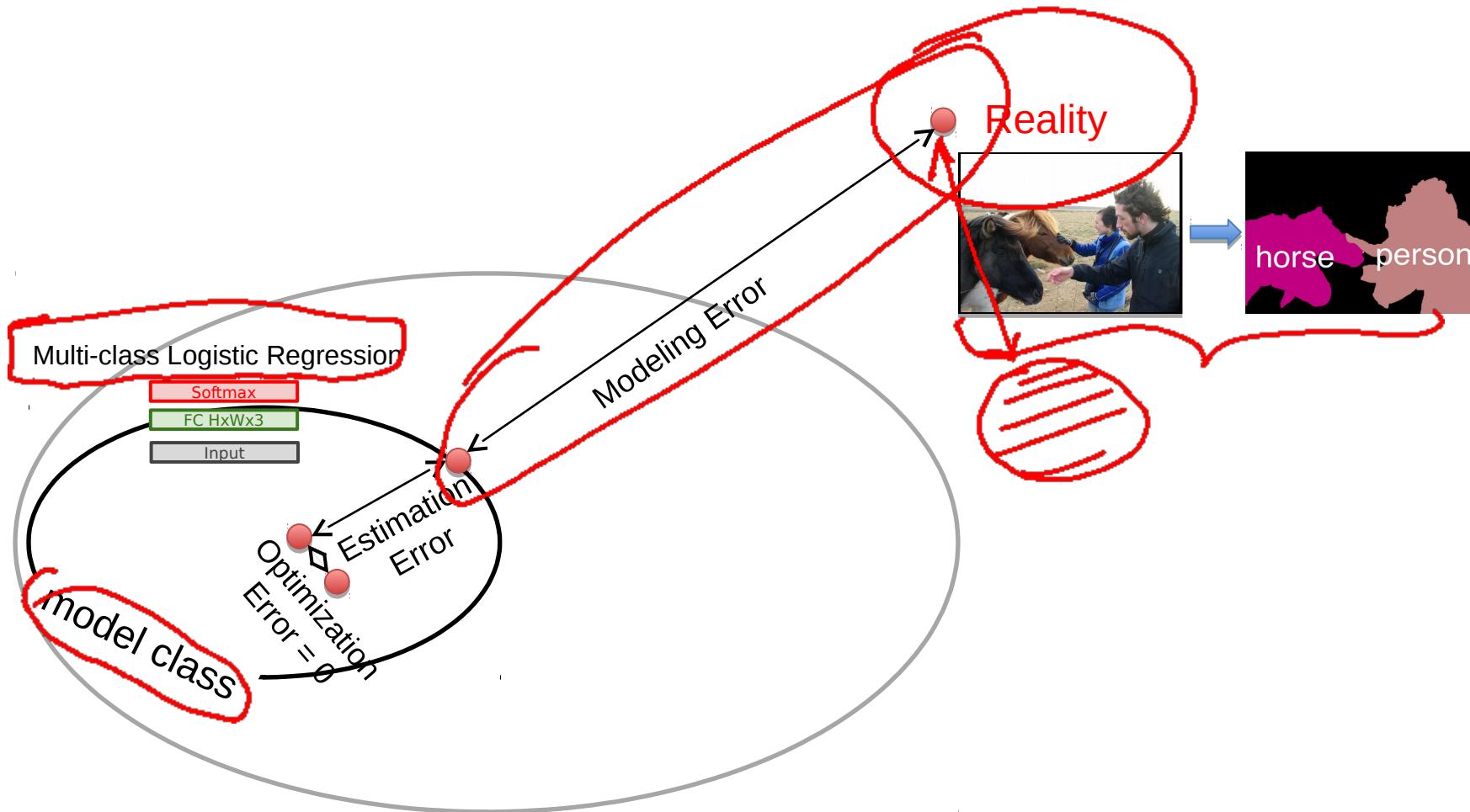
Dhruv Batra
Georgia Tech

Administrativia

- HW2 Reminder
 - Due: 09/23, 11:59pm
 - <https://evalai.cloudcv.org/web/challenges/challenge-page/684/leaderboard/1853>
- Project Teams
 - https://gtvault-my.sharepoint.com/:x/g/personal/dbatra8_gatech_edu/EY4_65XOzWtOkXSSz2WgpoUBY8ux2gY9PsRzR6KnglFEQ?e=4tnKWI
 - Project Title
 - 1-3 sentence project summary TL;DR
 - Team member names

Thoughts on Gaier & Ha NeurIPS19

Error Decomposition



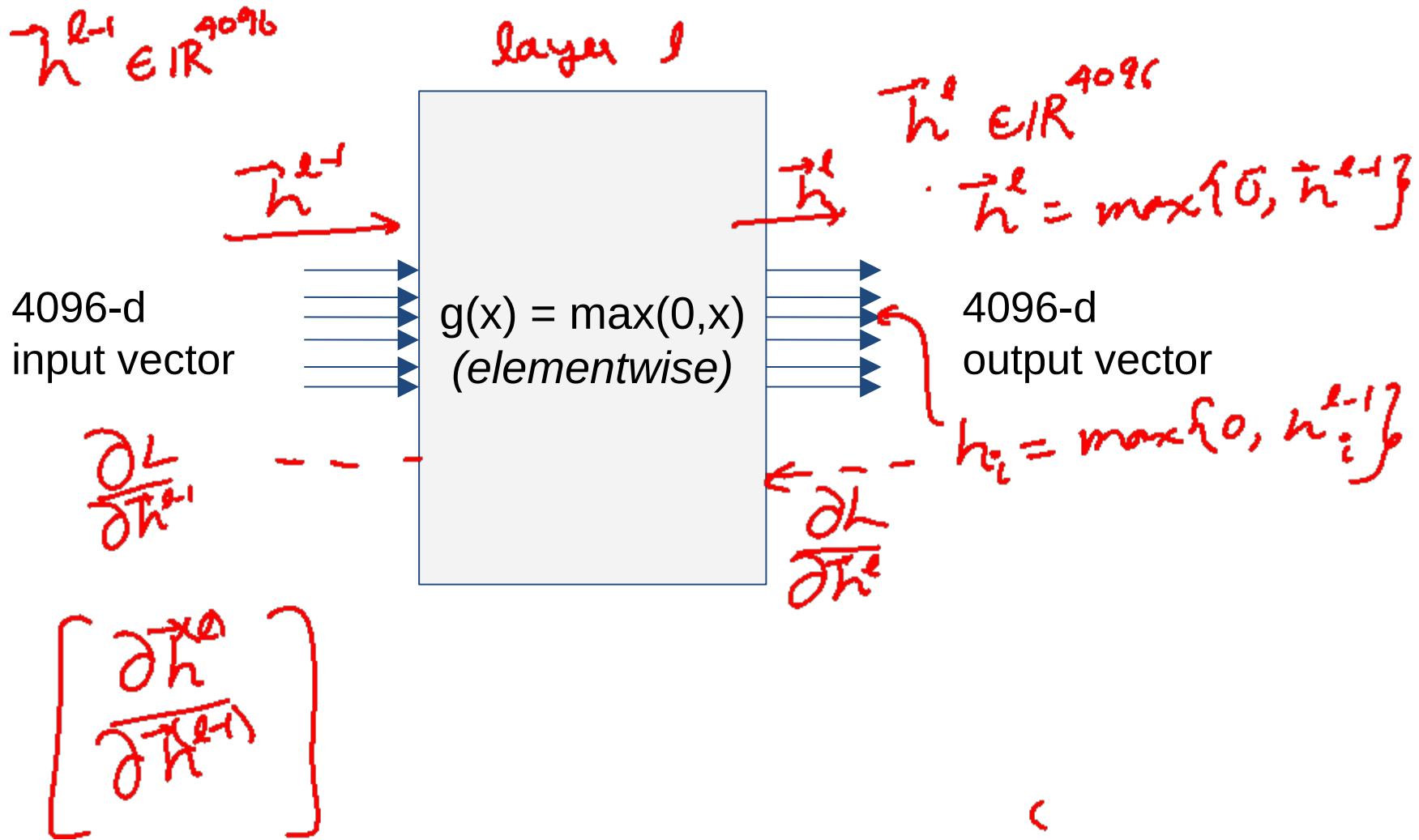
Thoughts on Gaier & Ha NeurIPS19

- Inductive biases
 - Nice timing wrt CNNs
 - See HW2 Q4
- Architecture elements as lego blocks
- Guest lecture on Neural Architecture Search
- Learned vs innate?

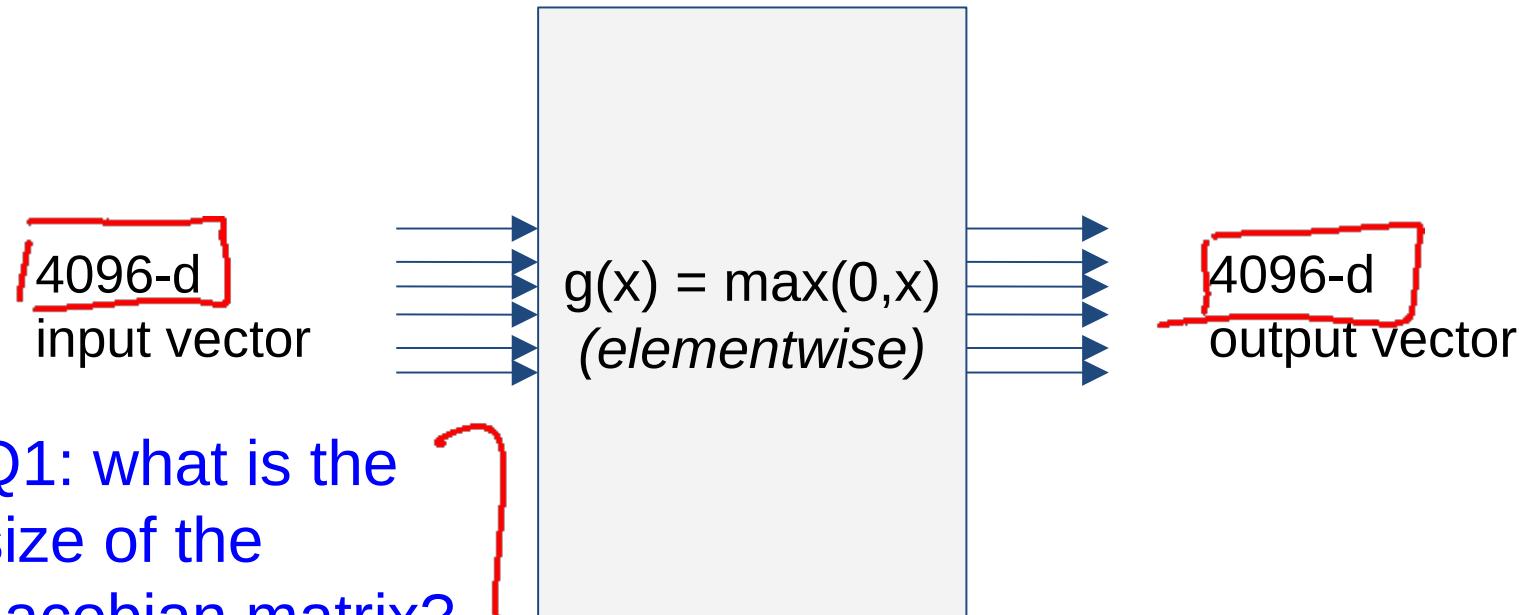
Plan for Today

- (Finish) Automatic Differentiation
 - Jacobians in FC+ReLU NNs
- Convolutional Neural Networks
 - What is a convolution?
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Jacobian of ReLU

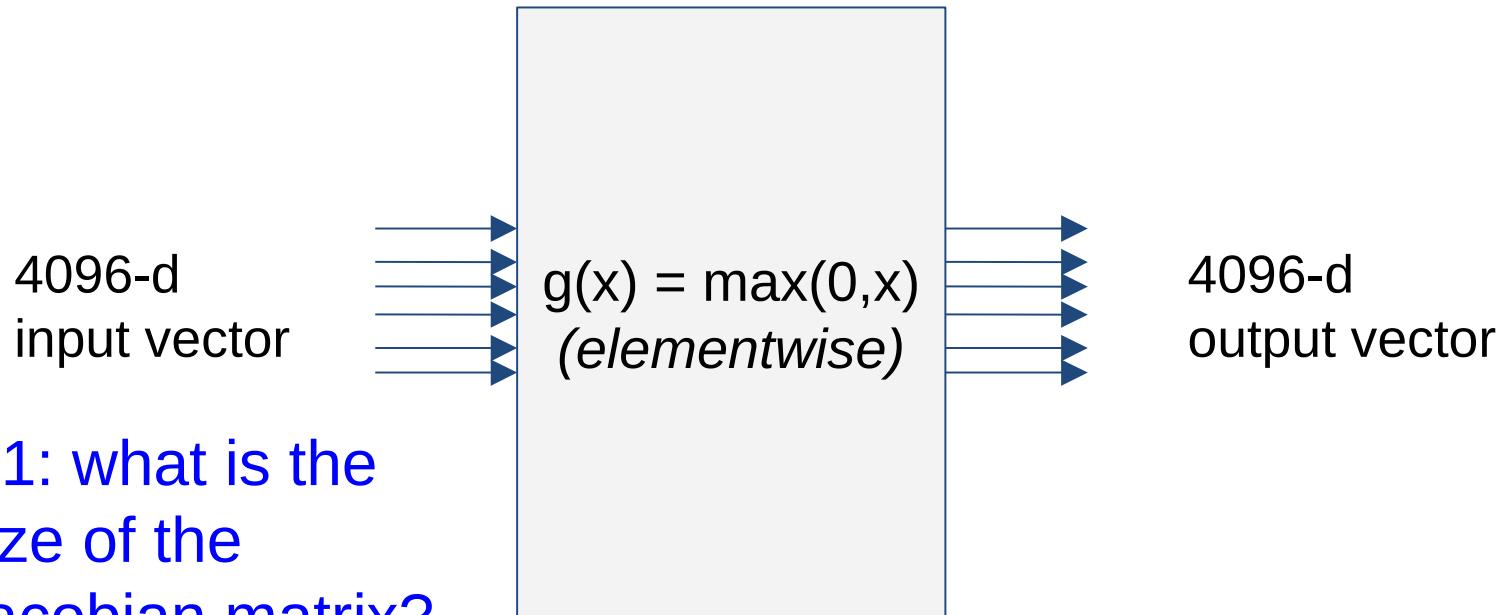


Jacobian of ReLU

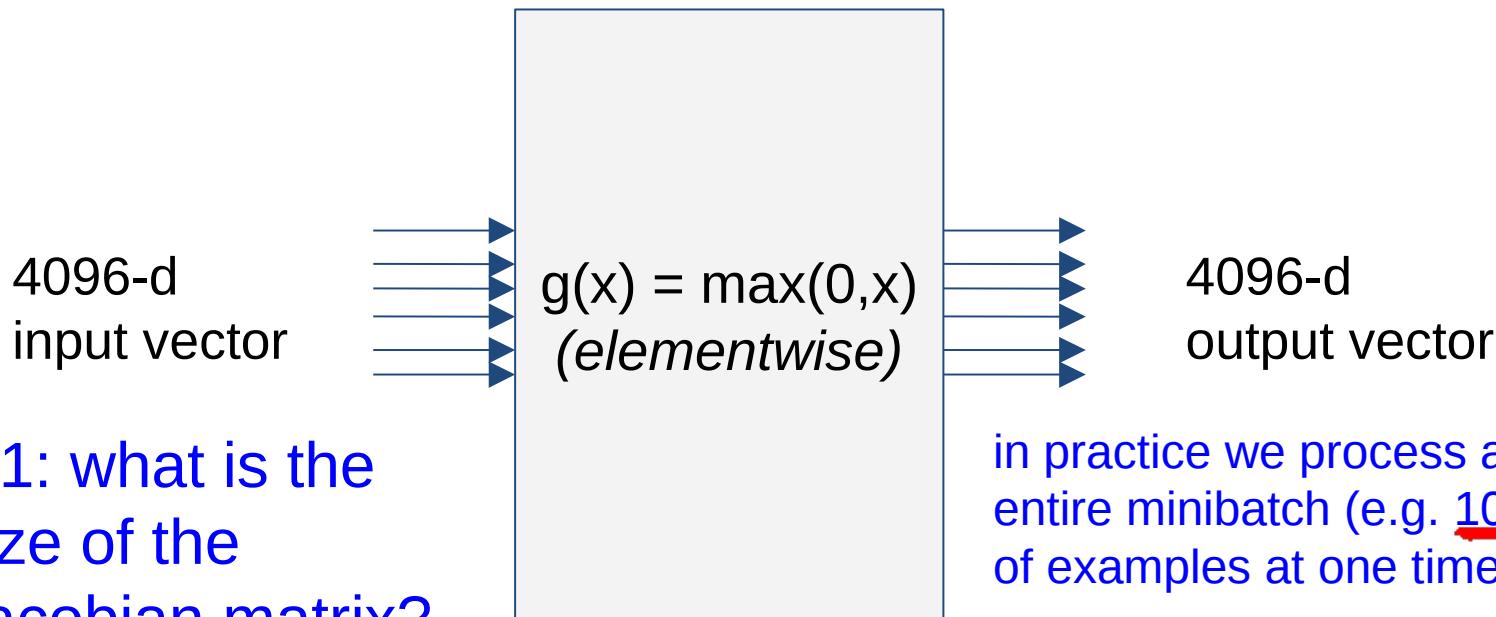


$$\frac{\partial \tilde{o}_l}{\partial \tilde{h}^{e-i}} \quad 4096 \times 4096$$

Jacobian of ReLU



Jacobian of ReLU

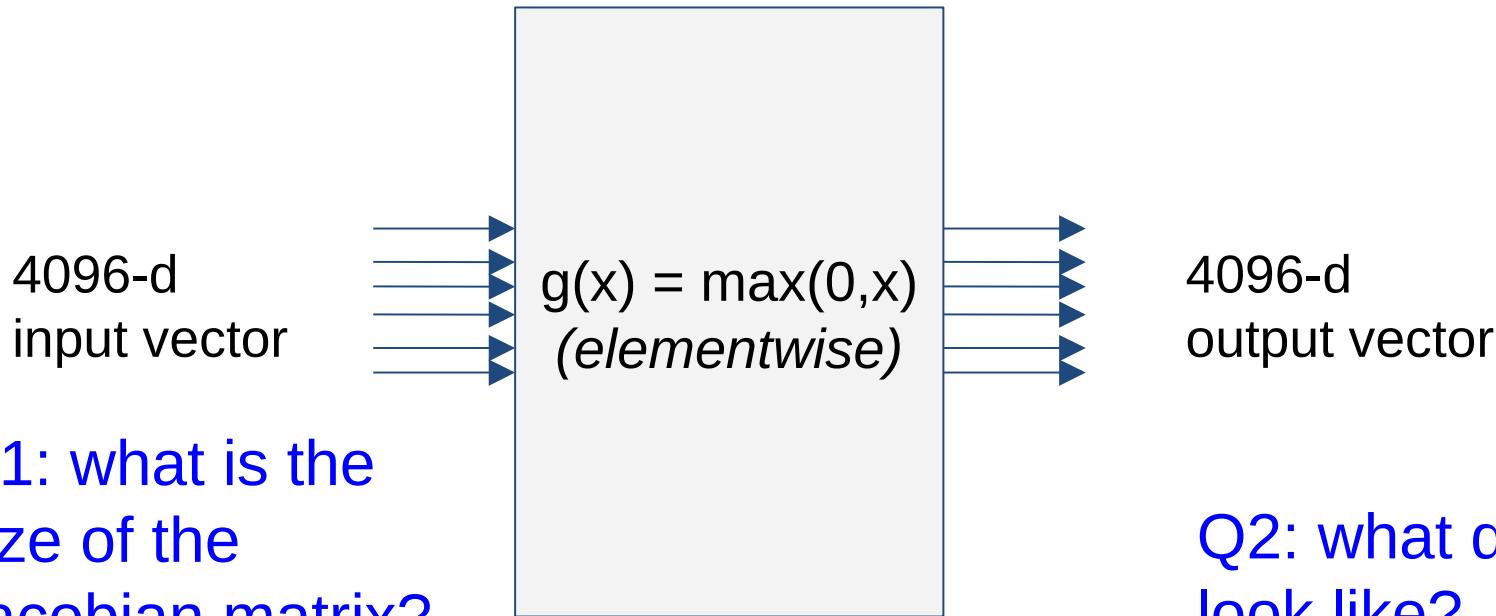


in practice we process an entire minibatch (e.g. 100) of examples at one time:

i.e. Jacobian would technically be a [409,600 x 409,600] matrix :\

Jacobian of ReLU

$$h_i^t = \max\{0, h_i^{t-1}\}$$



Q1: what is the size of the Jacobian matrix?

[4096 x 4096!]

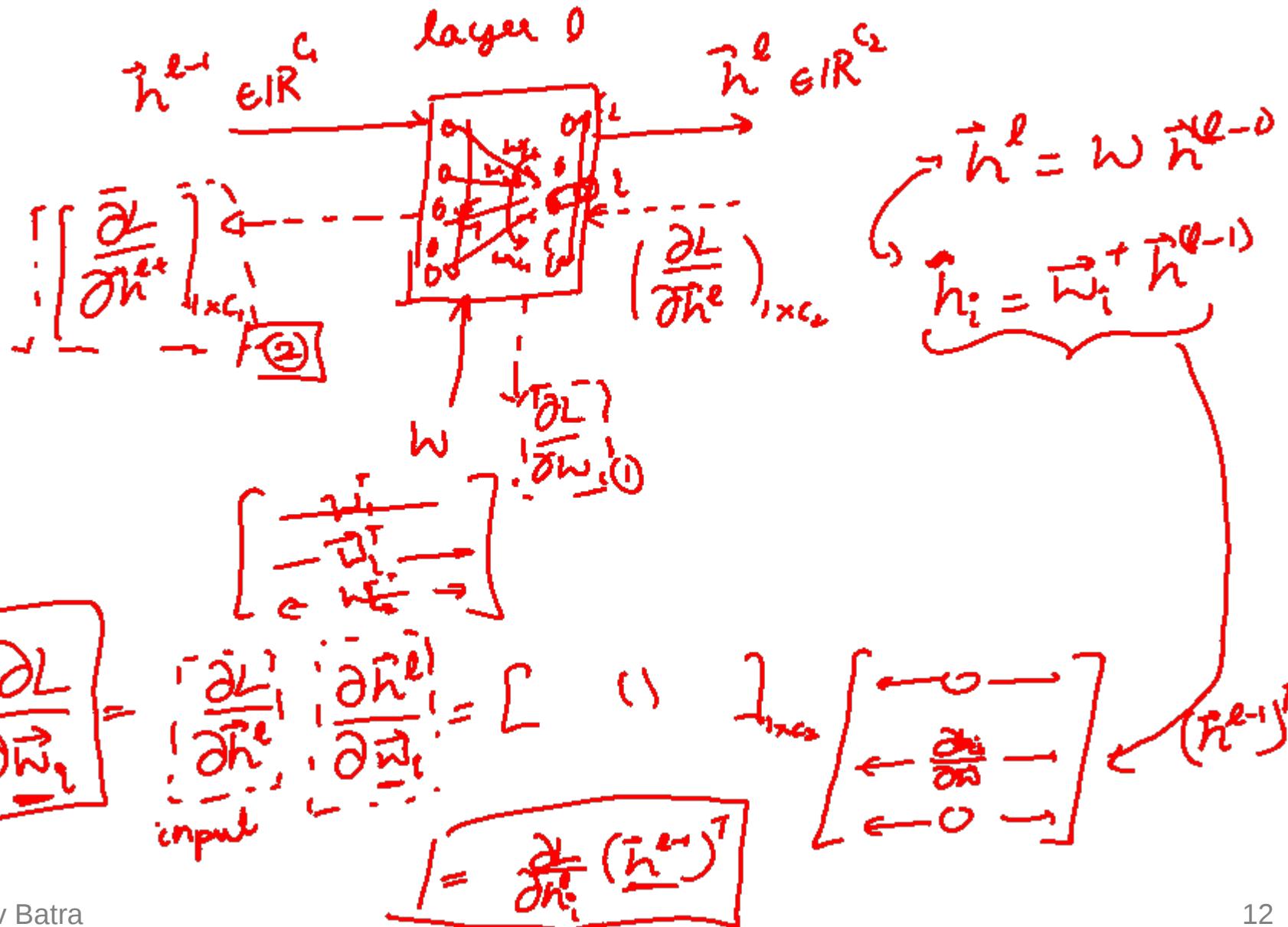
Q2: what does it look like?

$$\frac{\partial h^t}{\partial h^{t-1}} = \begin{bmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & \text{if } h_i^{t-1} > 0 & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{bmatrix}_{4096 \times 4096}$$

Annotations in red:

- $\frac{\partial h_i^t}{\partial h_i^{t-1}} = 0$ when $i \neq j$
- The matrix is labeled 4096×4096 .

Jacobians of FC-Layer



Jacobians of FC-Layer

$$\frac{\partial L}{\partial \vec{h}^{l+1}}$$

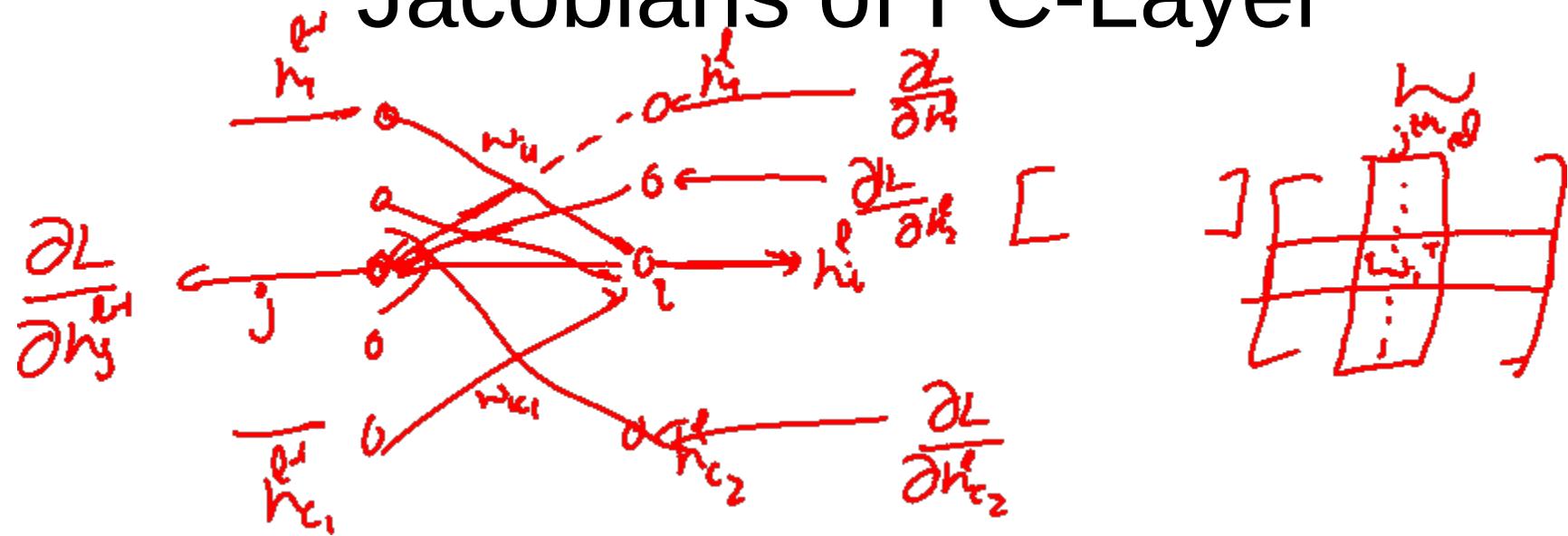
$$\vec{h}^l = \underline{w} \underline{\vec{h}^{l+1}}$$

$$\frac{\partial \vec{h}^l}{\partial \vec{h}^{l+1}} = w$$

$$= \frac{\partial L}{\partial \vec{h}^l} \cdot \frac{\partial \vec{h}^l}{\partial \vec{h}^{l+1}}$$



Jacobians of FC-Layer



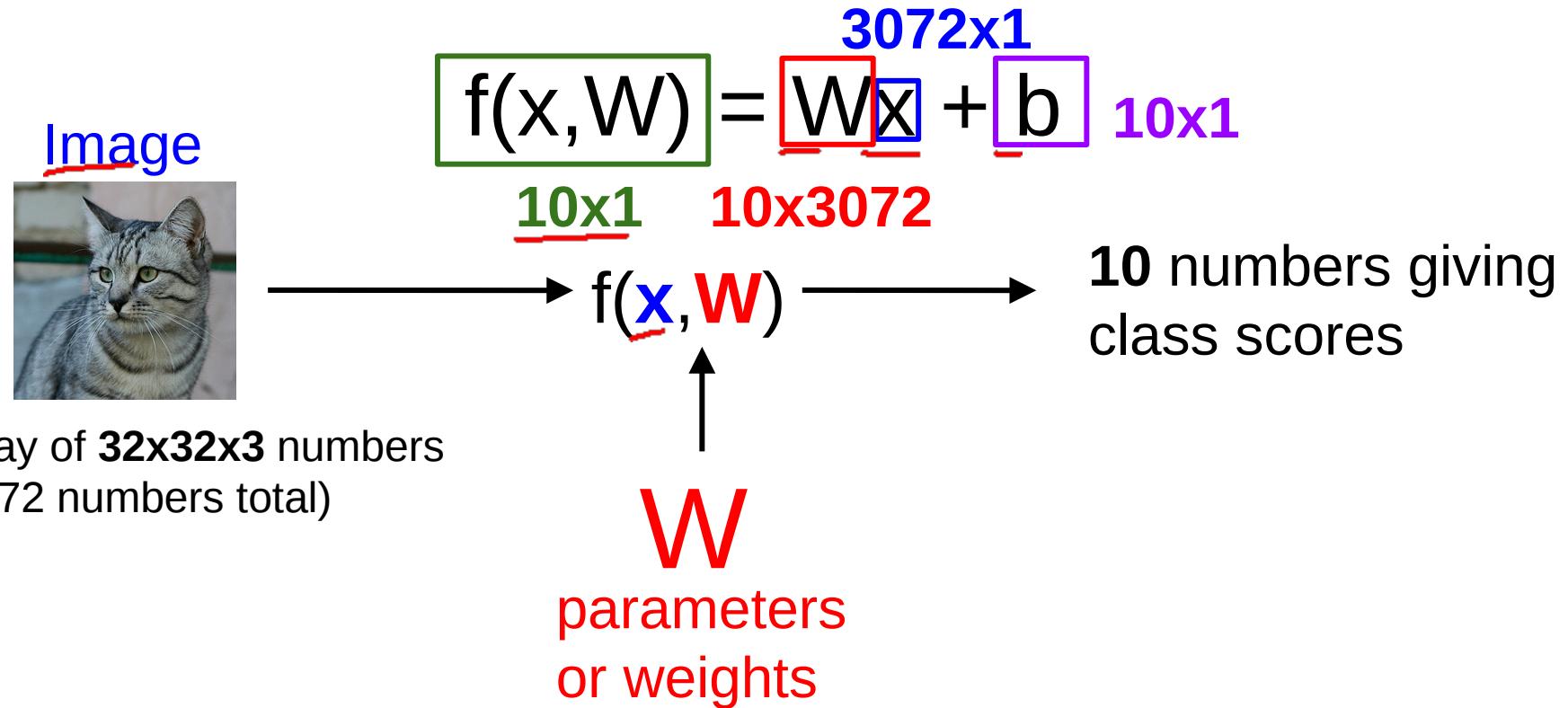
Plan for Today

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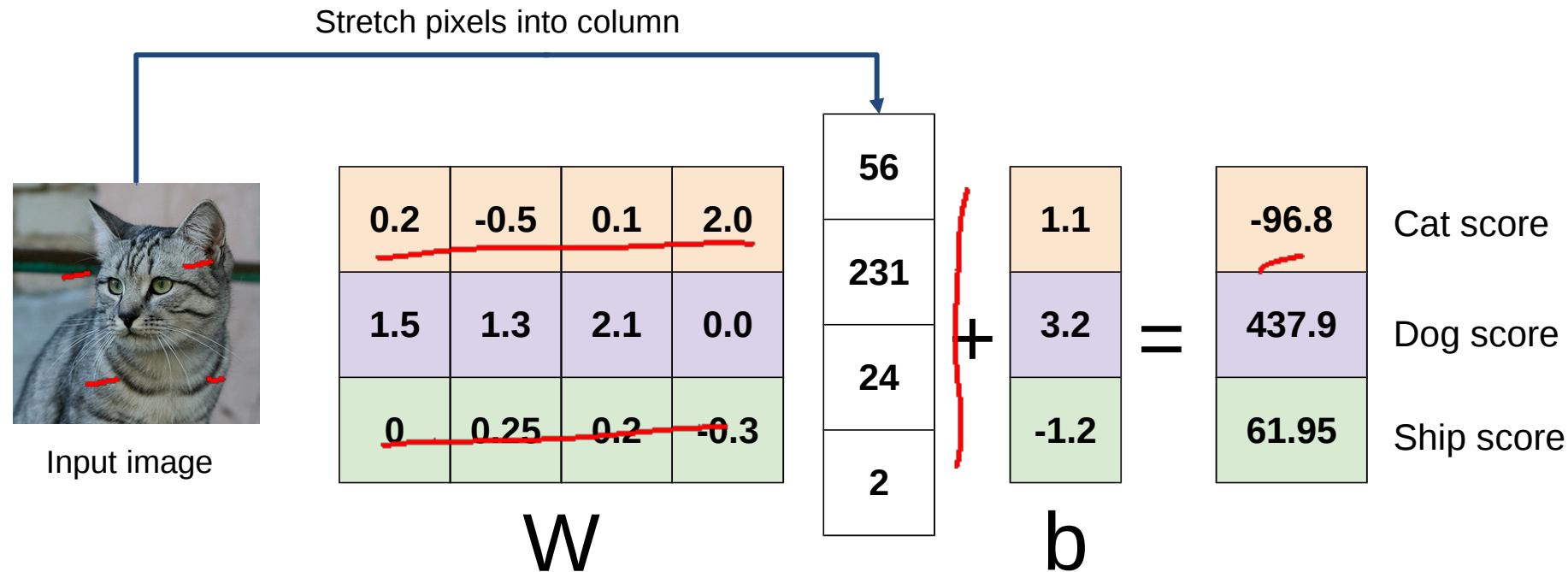
Plan for Today

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Recall: Linear Classifier



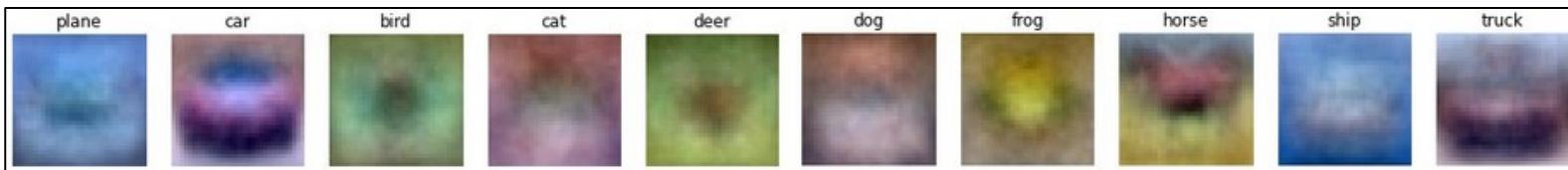
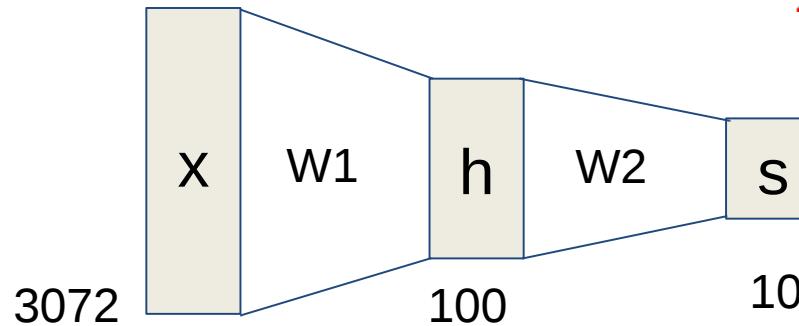
Example with an image with 4 pixels, and 3 classes (**cat/dog/ship**)



Recall: (Fully-Connected) Neural networks

(Before) Linear score function: $f = Wx$

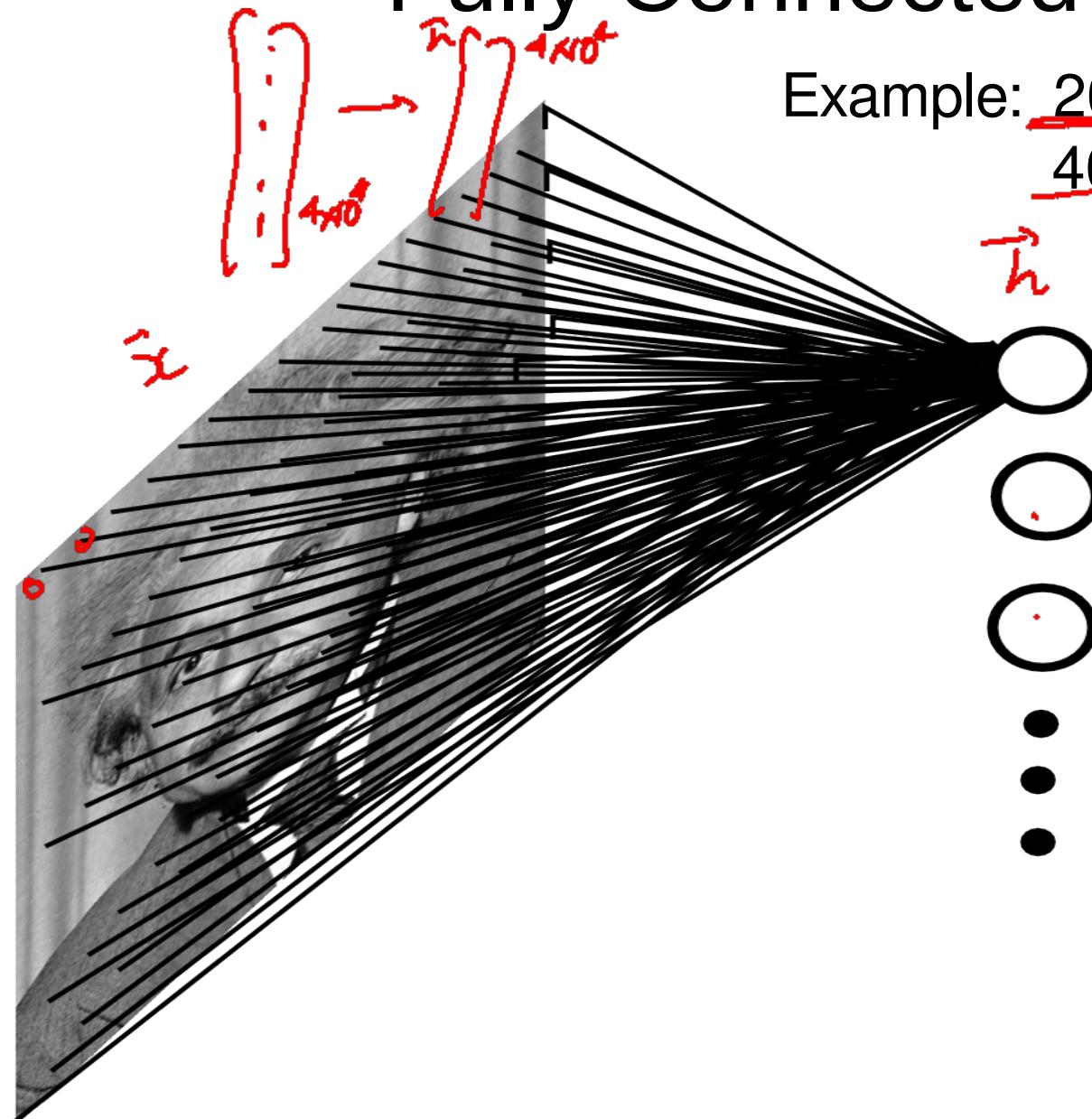
(Now) 2-layer Neural Network $f = W_2 \max(0, W_1 x)$



Convolutional Neural Networks

(without the brain stuff)

Fully Connected Layer



Example: 200x200 image
40K hidden units

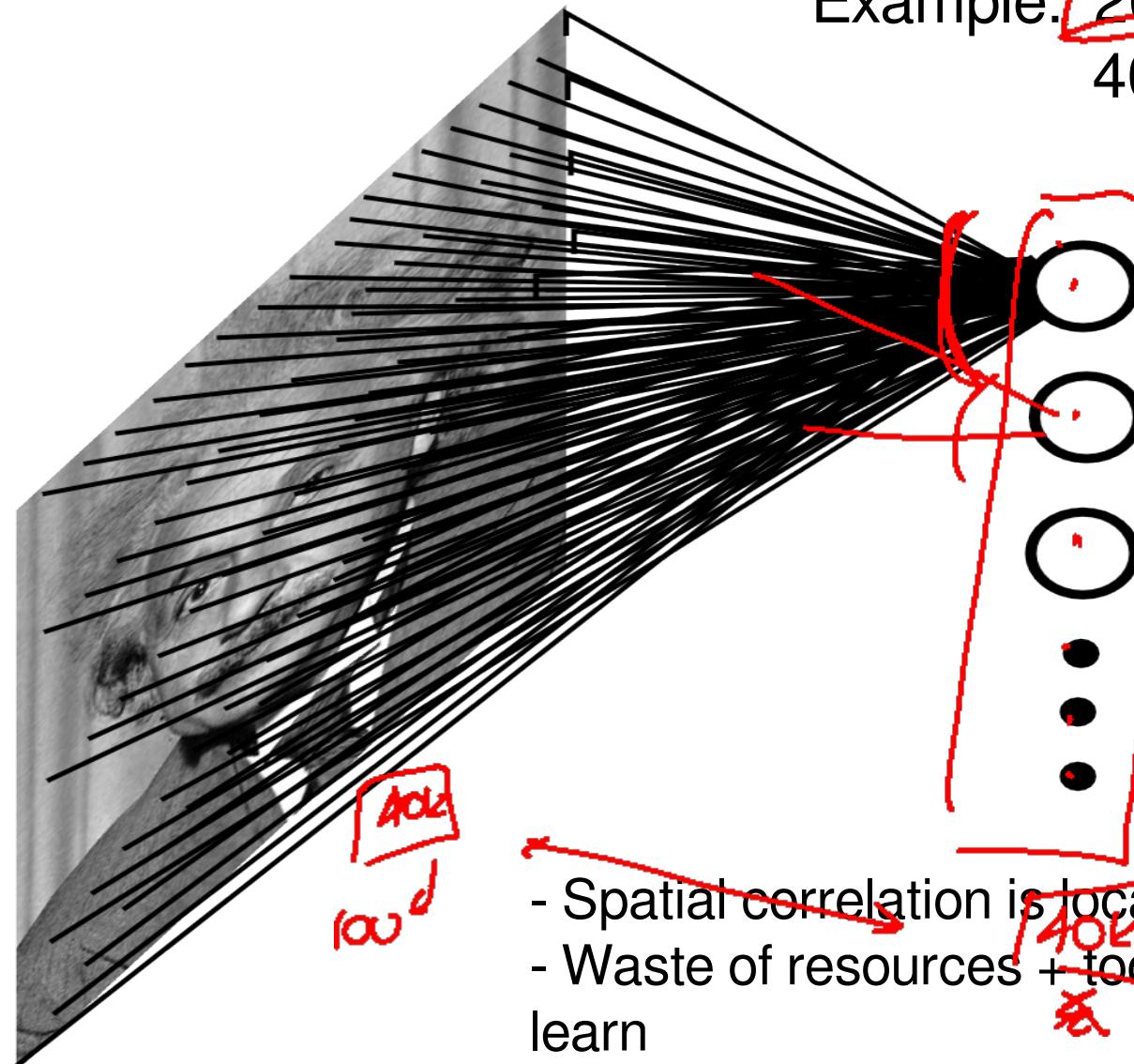
\hat{h}
Q: what is the number
of parameters in this
FC layer?

$$\left[\begin{array}{c} \\ \\ \\ \end{array} \right]_{16 \times 10^6}^{=} 40K \times 40K$$

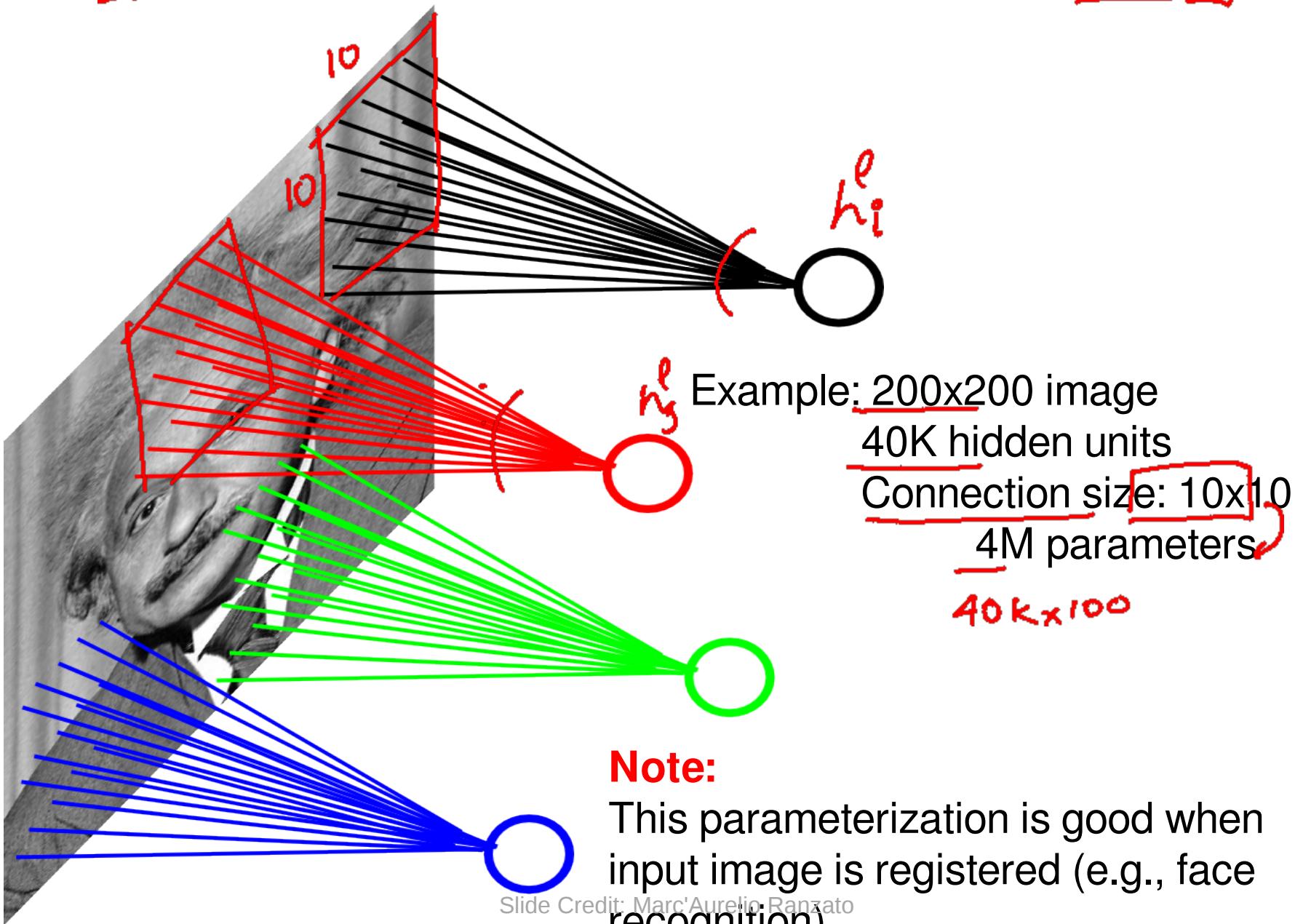
Fully Connected Layer

Example: ~~200x200 image~~
40K hidden units

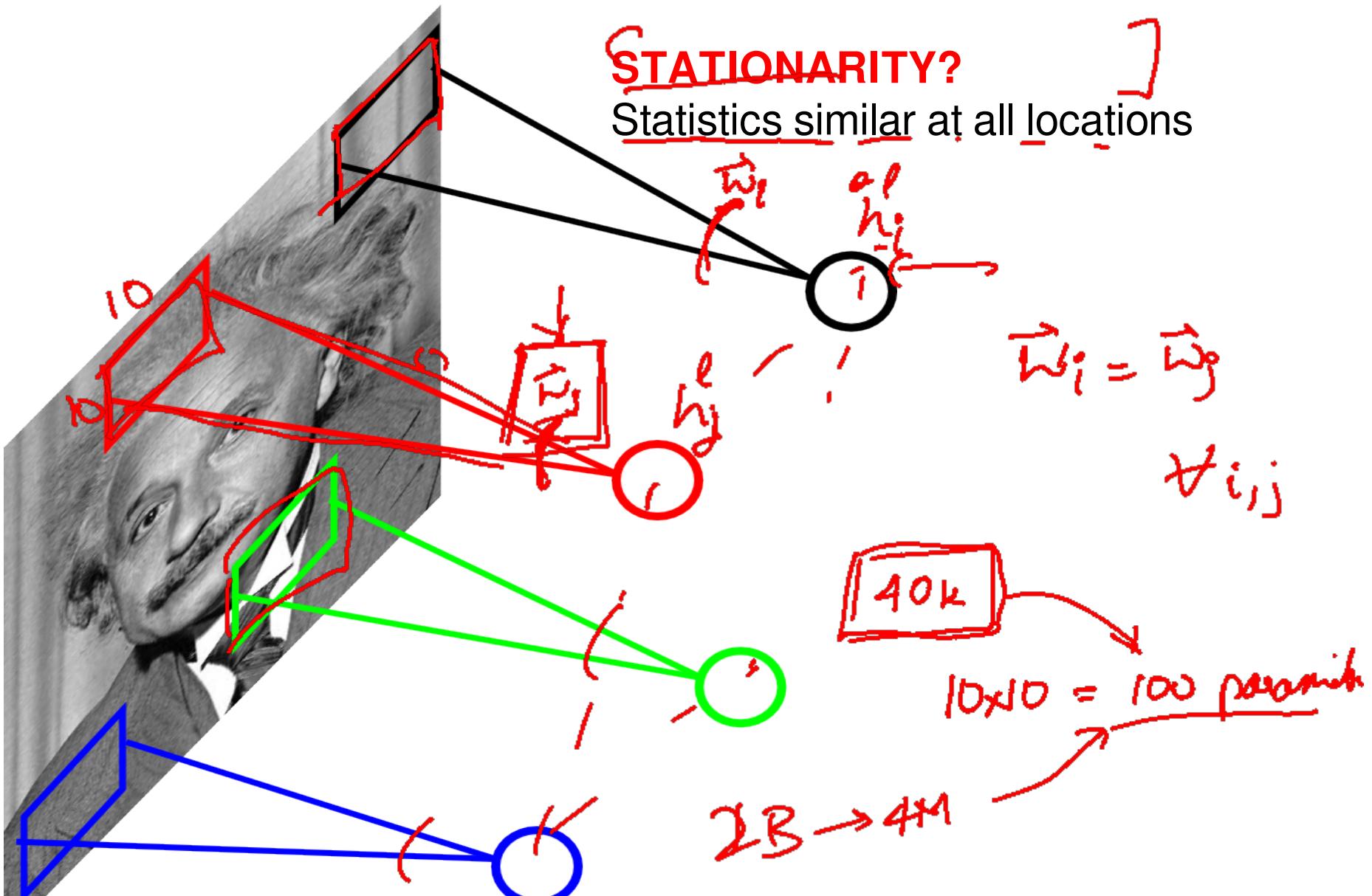
Q: what is the number
of parameters in this
FC layer?
A: ~ 2 Billion ~~1.6 B~~



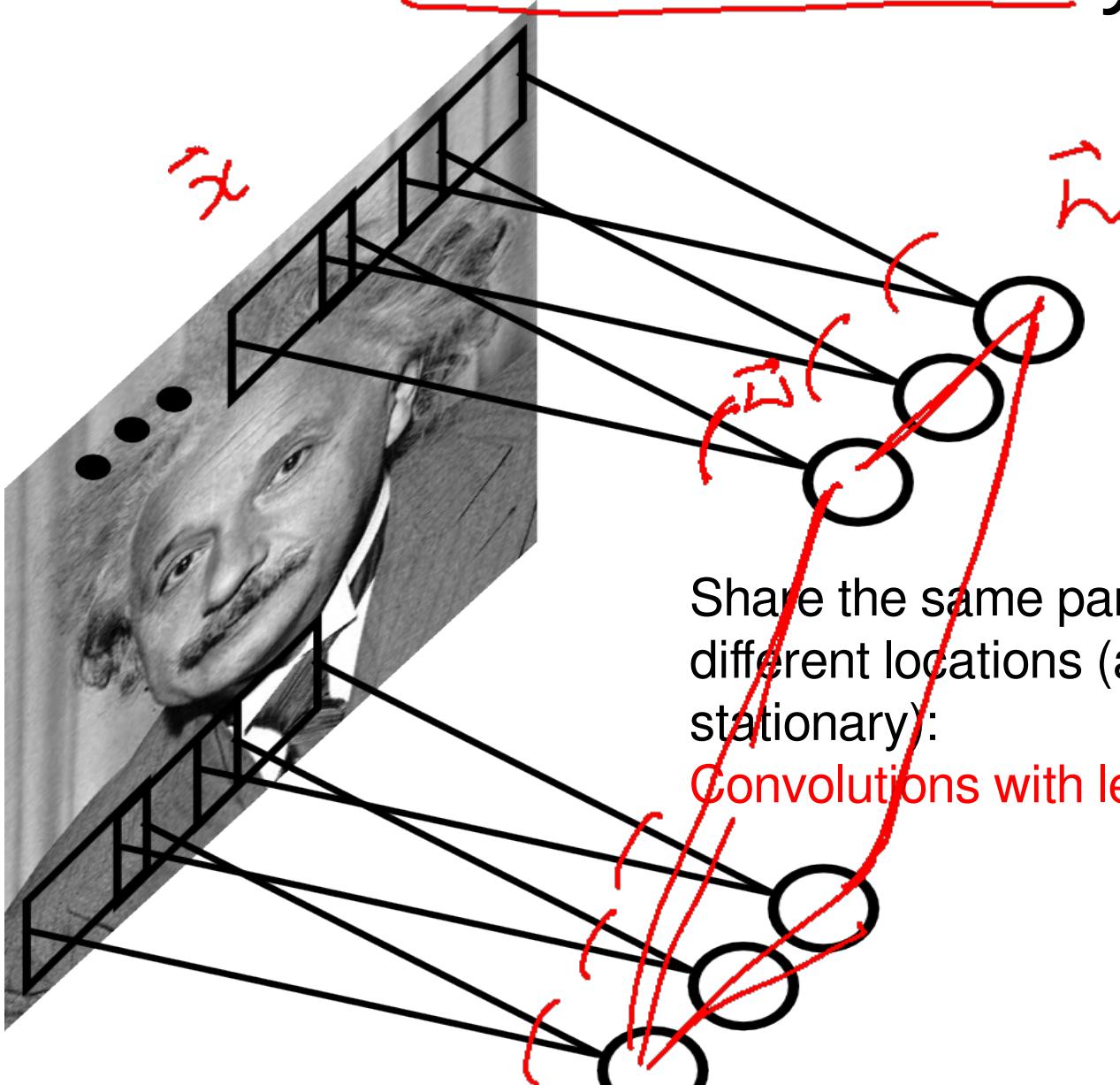
Assumption 1: Locally Connected Layer



Assumption 2: Stationarity / Parameter Sharing



Convolutional Layer



Share the same parameters across
different locations (assuming input is
stationary):
Convolutions with learned kernels

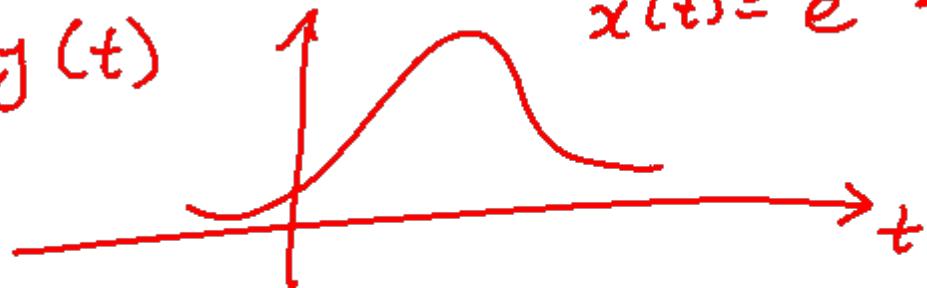


Convolutions!

math → CS → programming

Convolutions for mathematicians

$$x(t) \quad w(t) \quad y(t)$$

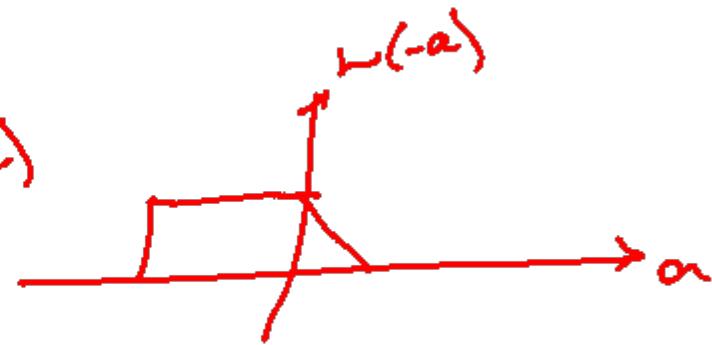
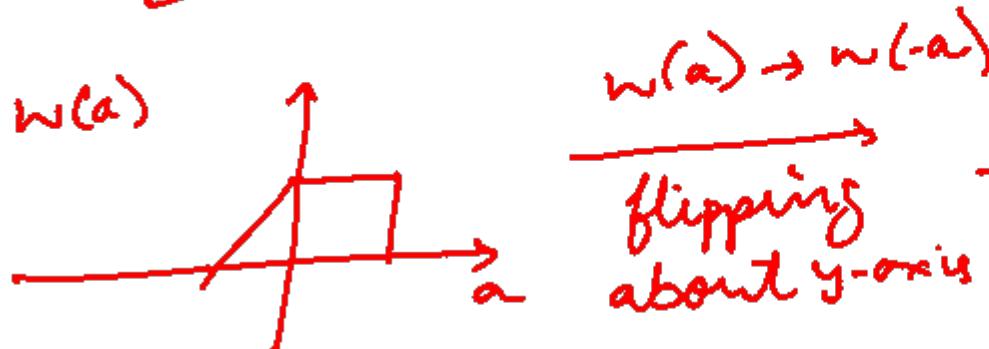


$$y(t) = (x * w)(t) = \int_{-\infty}^{\infty} x(t-a) w(a) da$$

$$= (w * x)(t) = \int_{-\infty}^{\infty} x(a) w(t-a) da$$

Convolutions for mathematicians

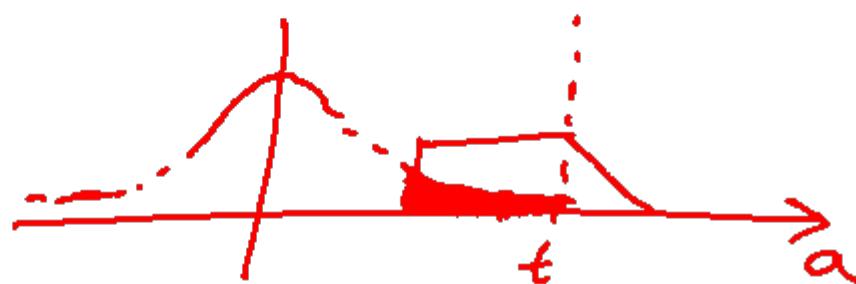
$$y(t) = \boxed{\int_{-\infty}^{\infty} x(a) w(t-a) da}$$



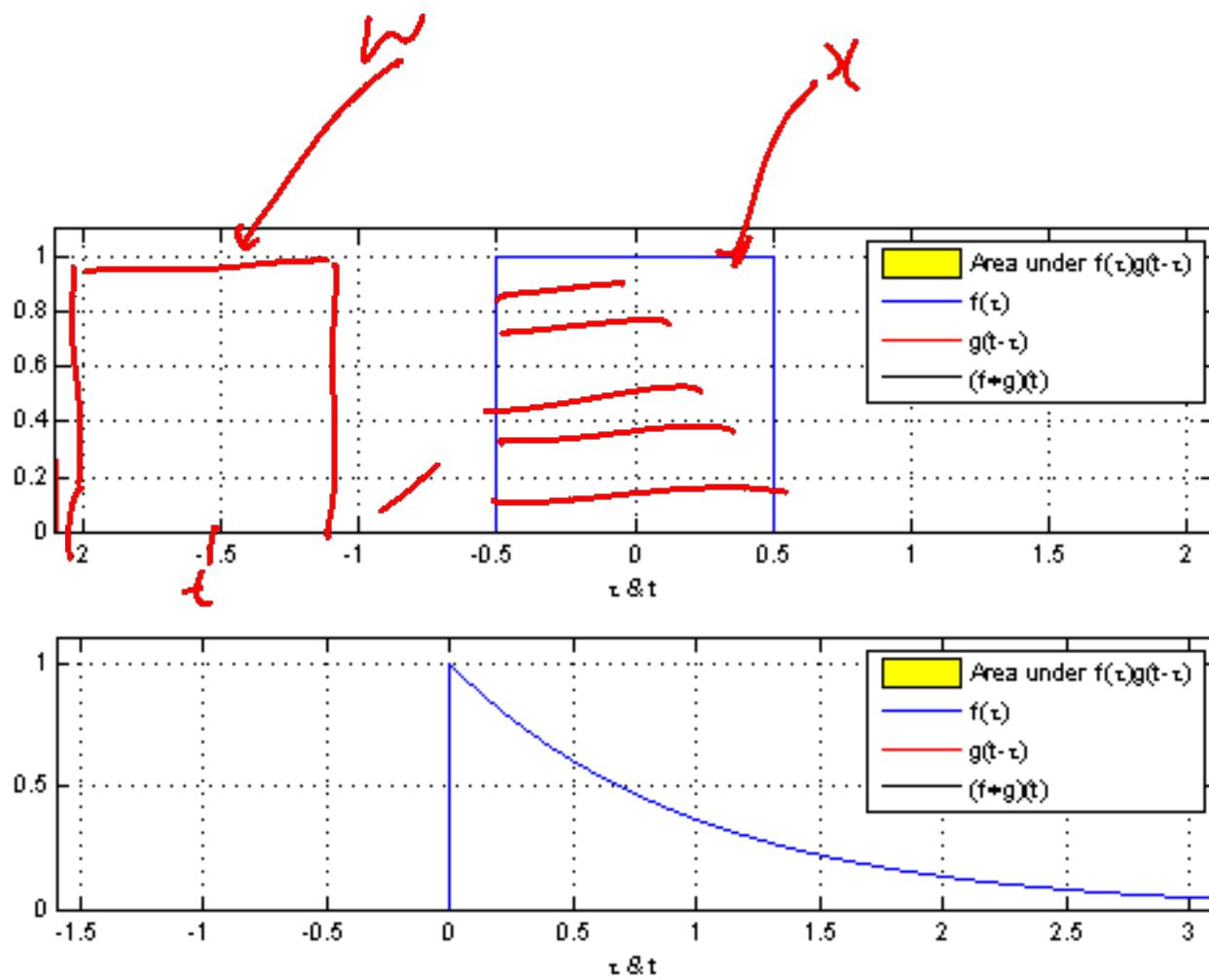
$w(a) \rightarrow w(-a)$
flipping
about y-axis

time shifting
by t

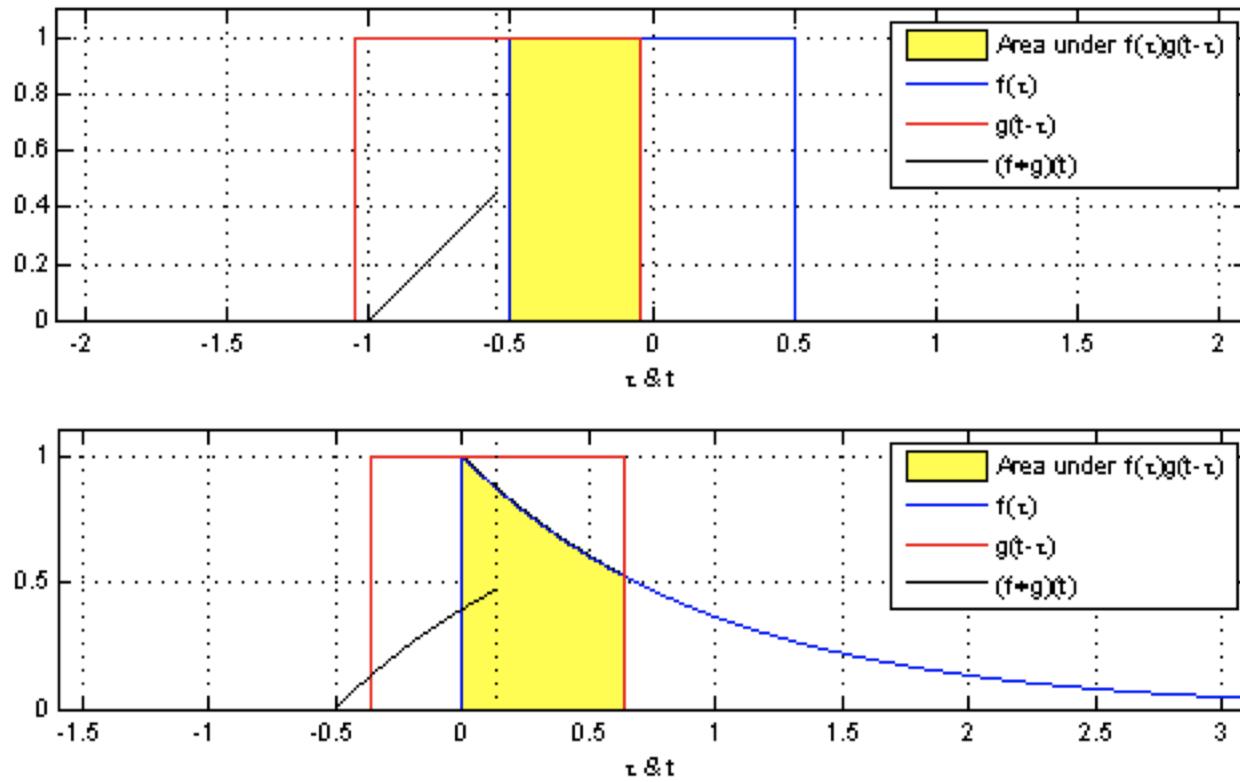
$$w(-a) \rightarrow w(-(a-t))$$



$y(t)$



"Convolution of box signal with itself2" by Convolution_of_box_signal_with_itself.gif: Brian Amberg derivative work: Tinos (talk)
 - Convolution_of_box_signal_with_itself.gif. Licensed under CC BY-SA 3.0 via Commons
https://commons.wikimedia.org/wiki/File:Convolution_of_box_signal_with_itself2.gif#/media/File:Convolution_of_box_signal_with_itself2.gif
 (C) Dhruv Batra



"Convolution of box signal with itself2" by Convolution_of_box_signal_with_itself.gif: Brian Amberg derivative work: Tinos (talk)
 - Convolution_of_box_signal_with_itself.gif. Licensed under CC BY-SA 3.0 via Commons -

https://commons.wikimedia.org/wiki/File:Convolution_of_box_signal_with_itself2.gif#/media/File:Convolution_of_box_signal_with_itself2.gif

Convolutions for mathematicians

- One dimension

$$y(t) = \int_{-\infty}^{\infty} x(t-a) w(a) da$$

- Two dimensions

$$y(t_1, t_2) = \iint_{\substack{a=-\infty \\ b=-\infty}}^{\infty \infty} x(\underline{t_1 - a}, \underline{t_2 - b}) w(a, b) da db$$

Convolutions for computer scientists

① No inf proc $SS \rightarrow \Sigma \Sigma$

$$y[t_1, t_2] = \sum_{a=-\infty}^{\infty} \sum_{b=-\infty}^{\infty} x[t_1-a, t_2-b] w[a, b]$$

② No inf memory

$$\begin{matrix} \leftarrow N_2 \rightarrow \\ \downarrow \quad \uparrow \\ \text{---} \end{matrix} \quad \begin{matrix} \leftarrow k_2 \rightarrow \\ \downarrow \quad \uparrow \\ \text{---} \end{matrix} =$$

x w

$$y[t_1, t_2] = \sum_{a=-\frac{k_2-1}{2}}^{\frac{k_2-1}{2}} \sum_{b=-\frac{k_2-1}{2}}^{\frac{k_2-1}{2}}$$

()

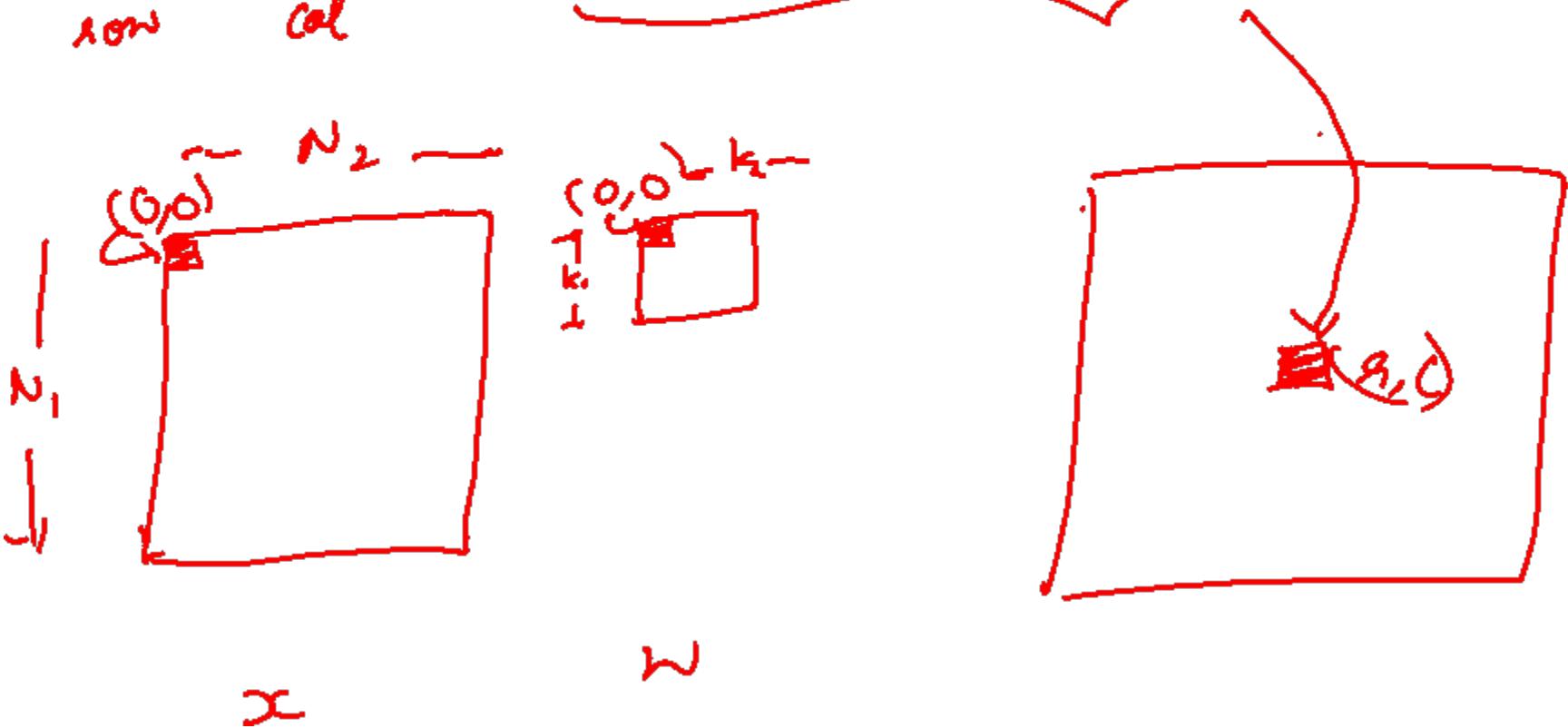
$y[t_1, t_2]$

Convolutions for computer scientists

Convolutions for programmers

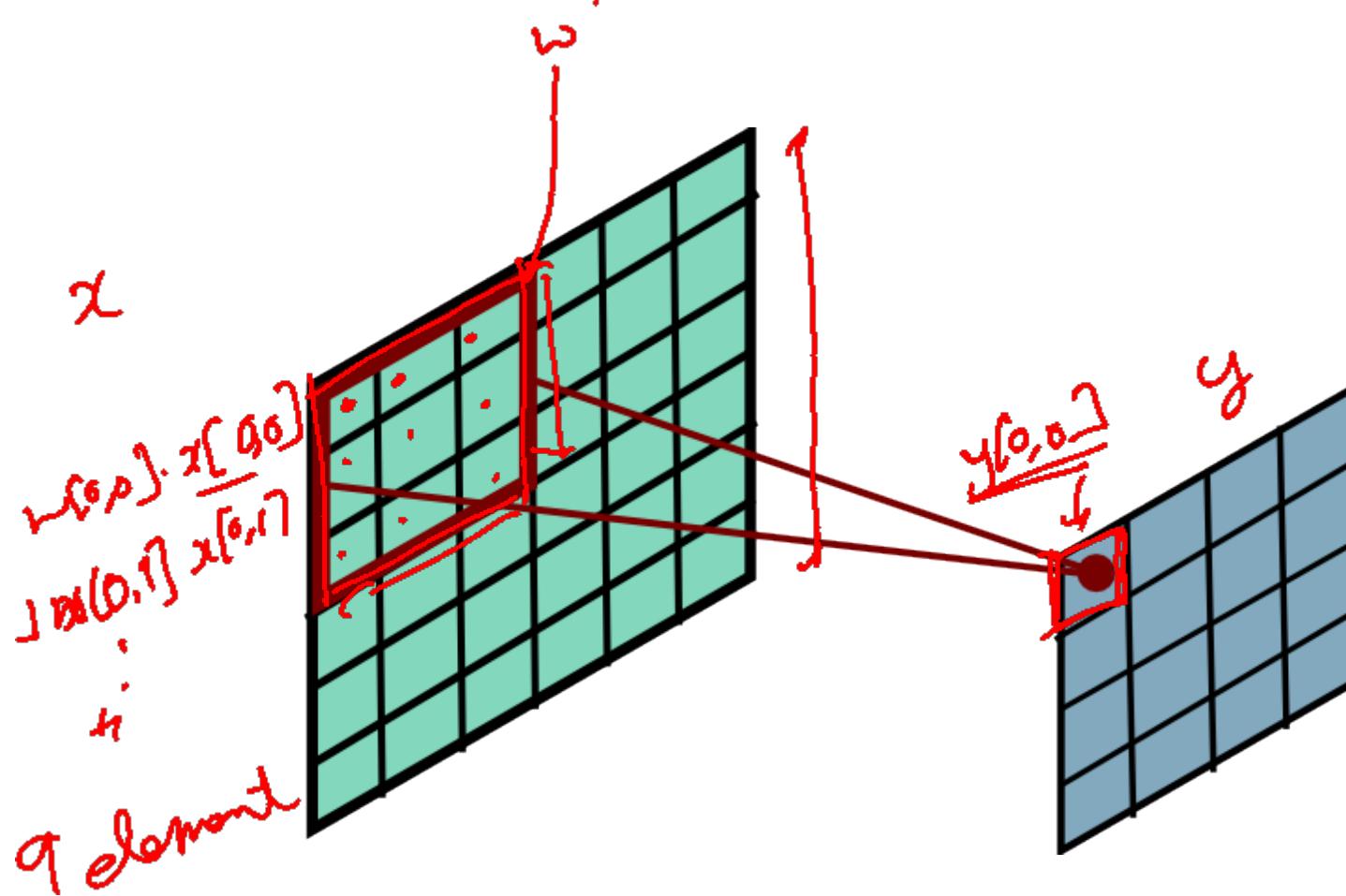
$$y[a, c] = \sum_{\alpha=0}^{k_1-1} \sum_{\beta=0}^{k_2-1} x[a+\alpha, c+\beta] w[\alpha, \beta]$$

row col

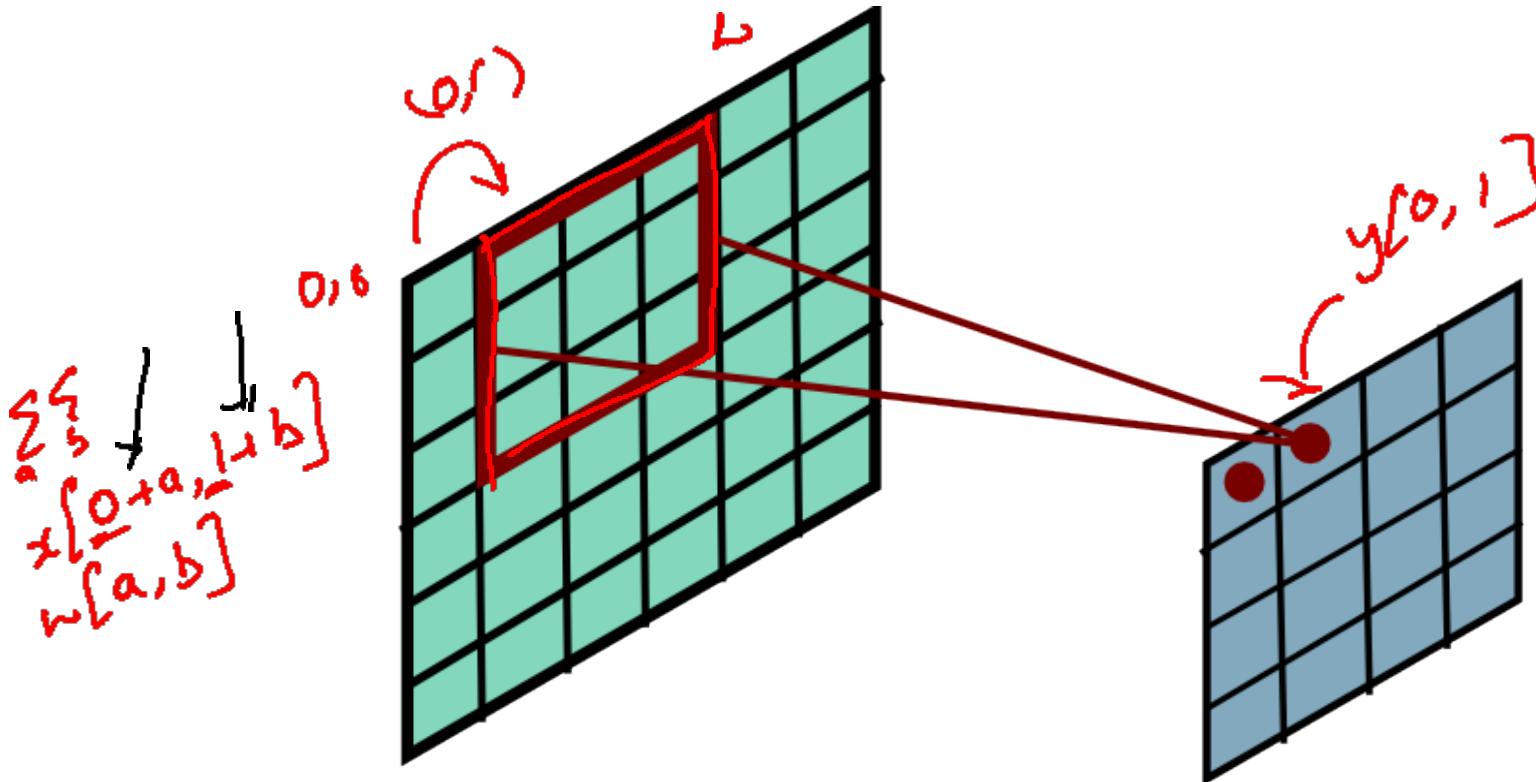


Convolutions for programmers

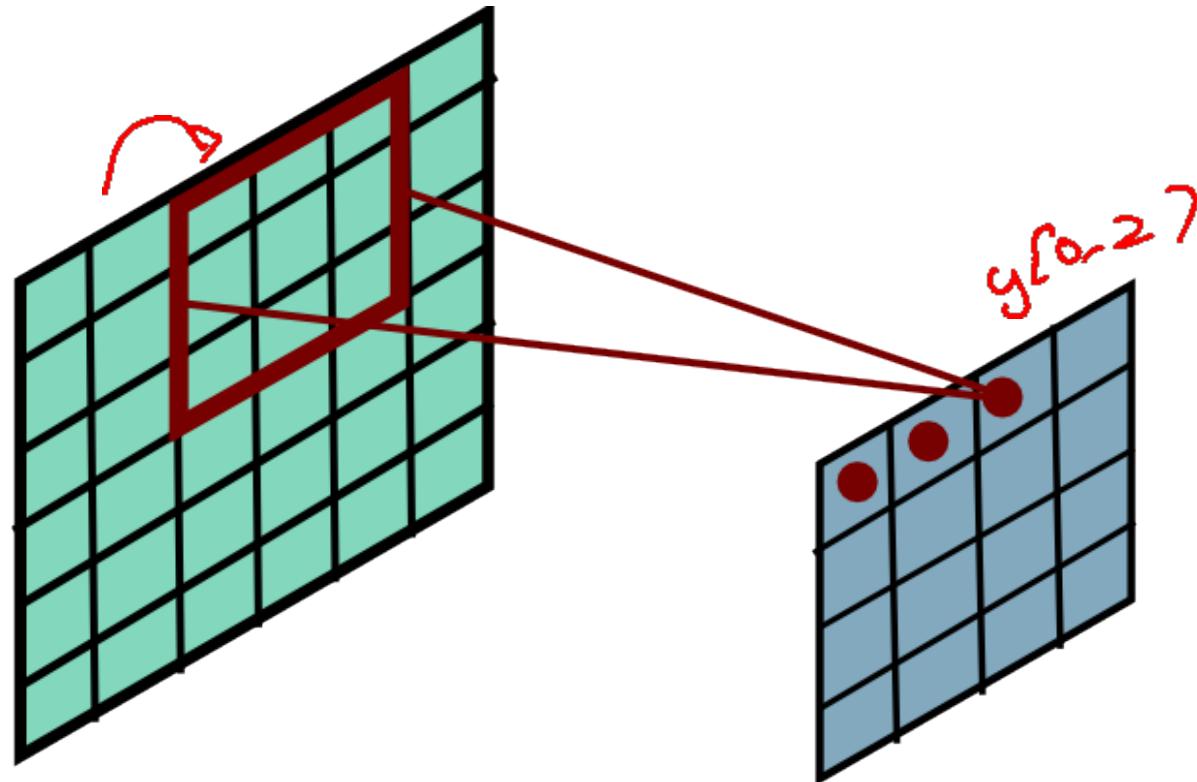
Convolutional Layer



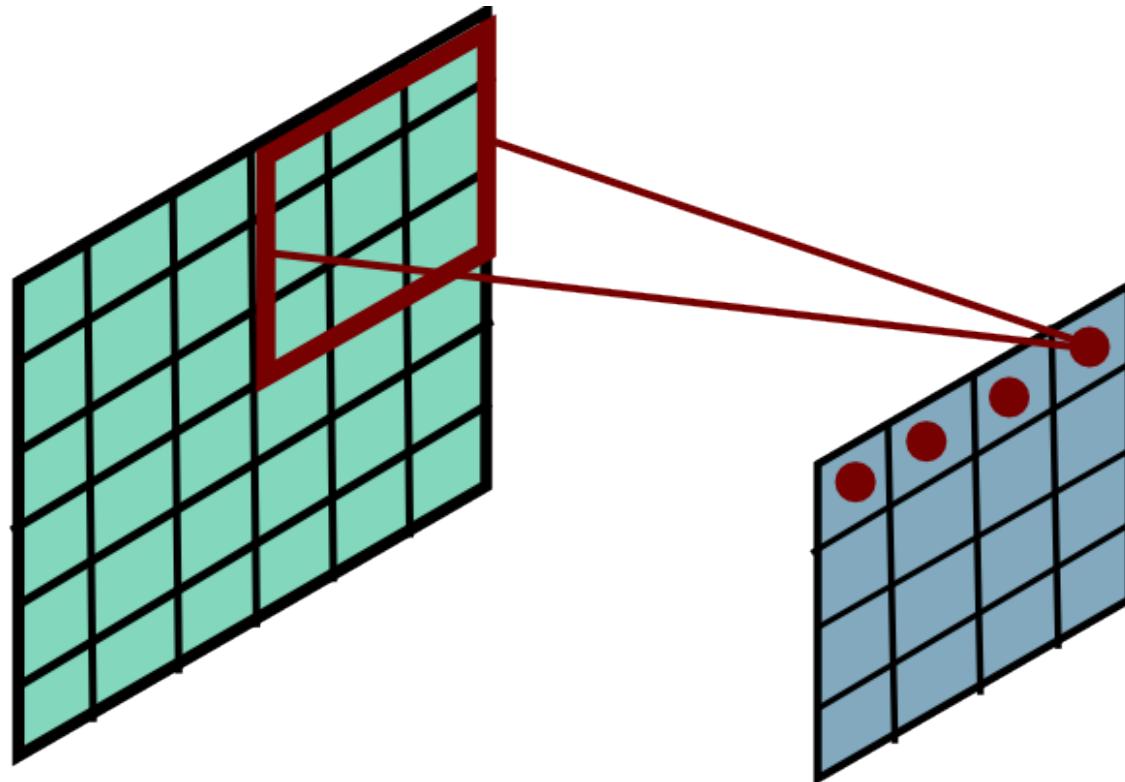
Convolutional Layer



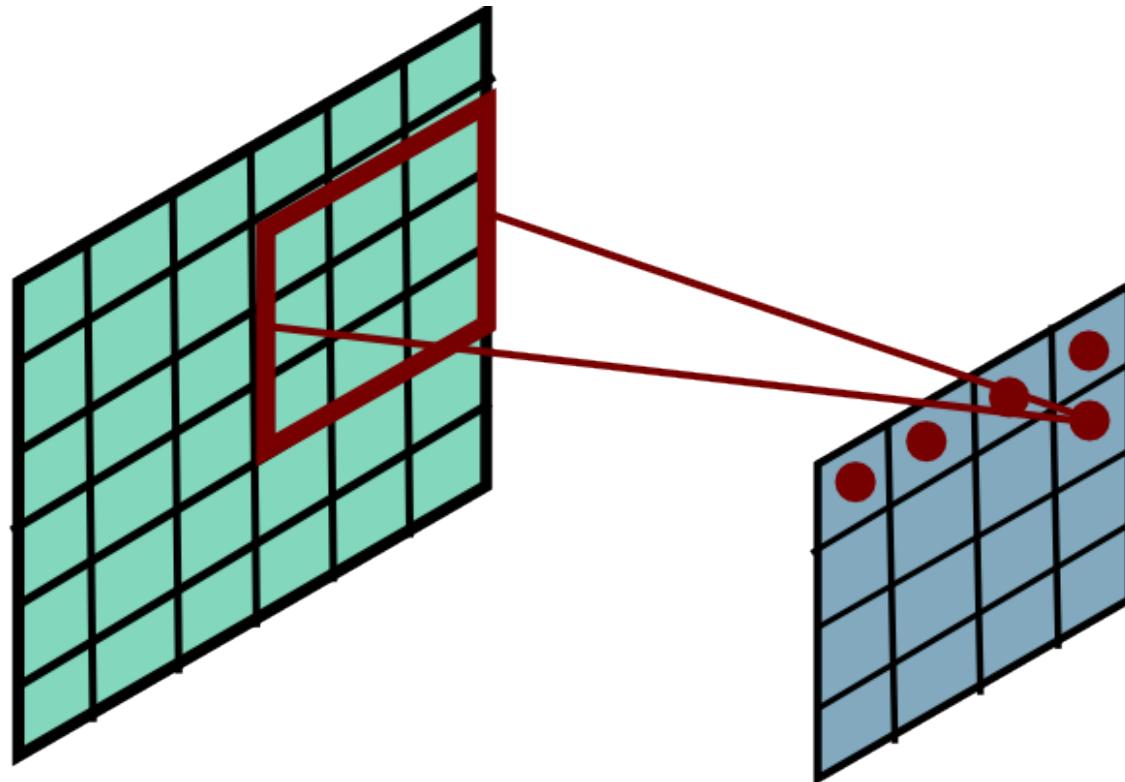
Convolutional Layer



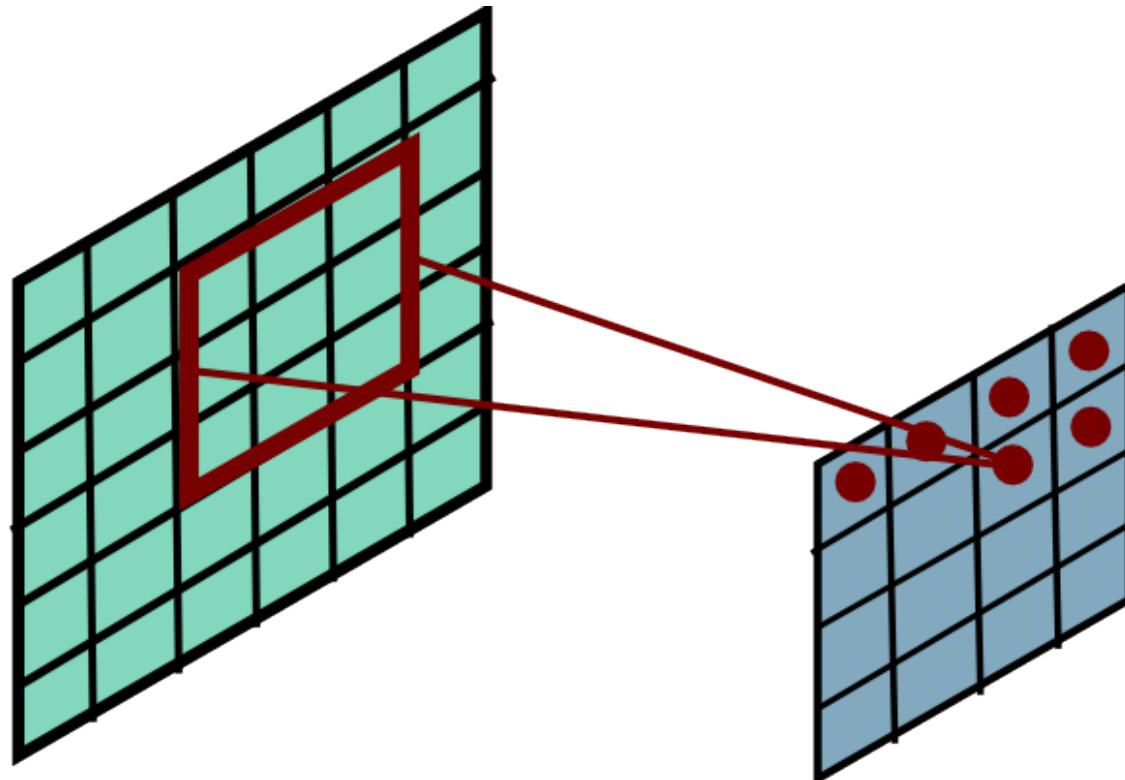
Convolutional Layer



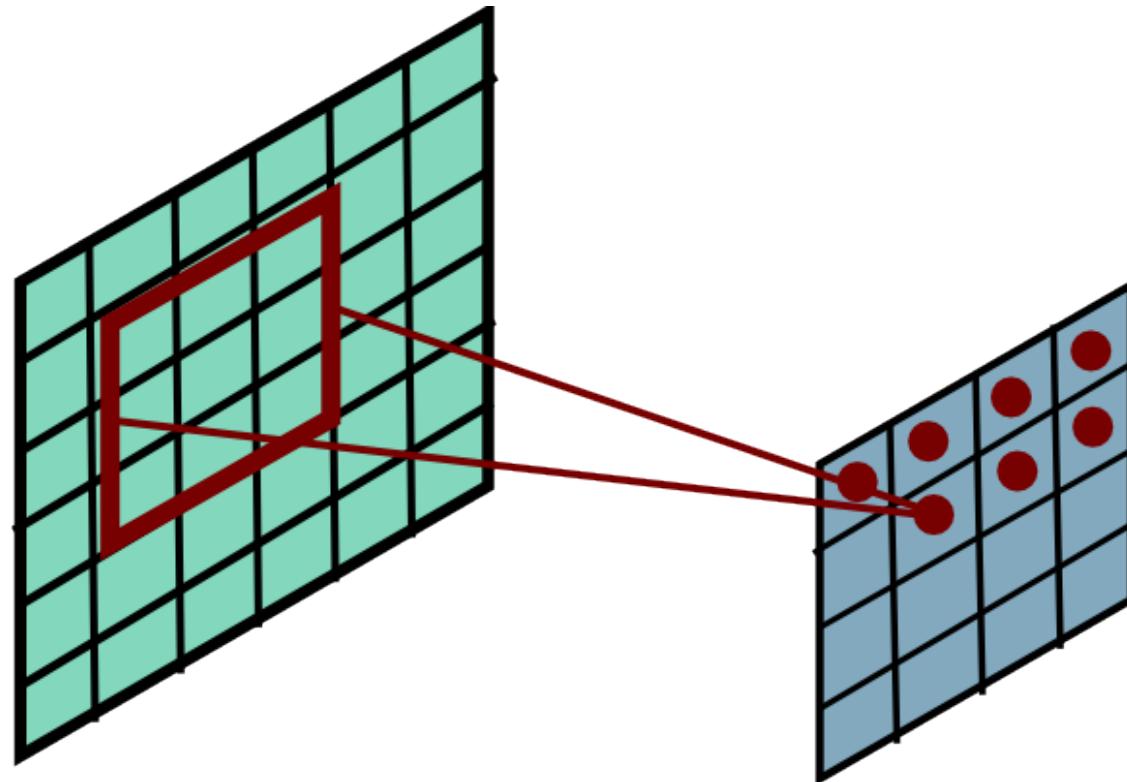
Convolutional Layer



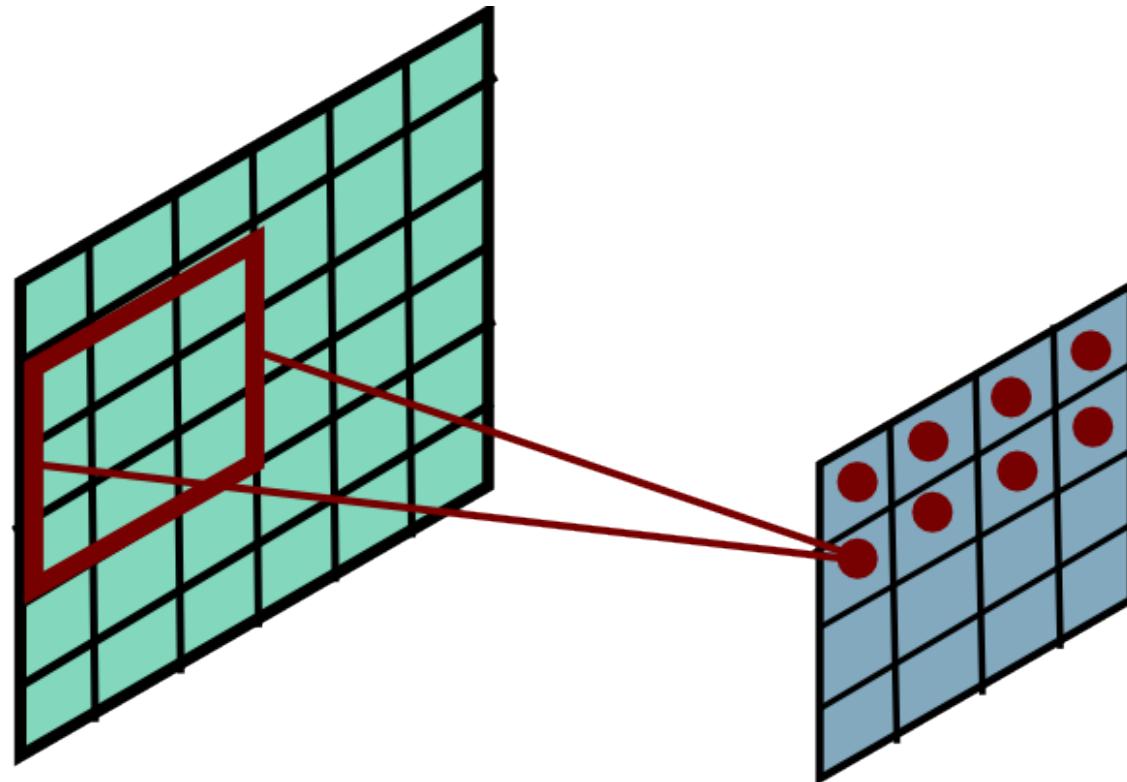
Convolutional Layer



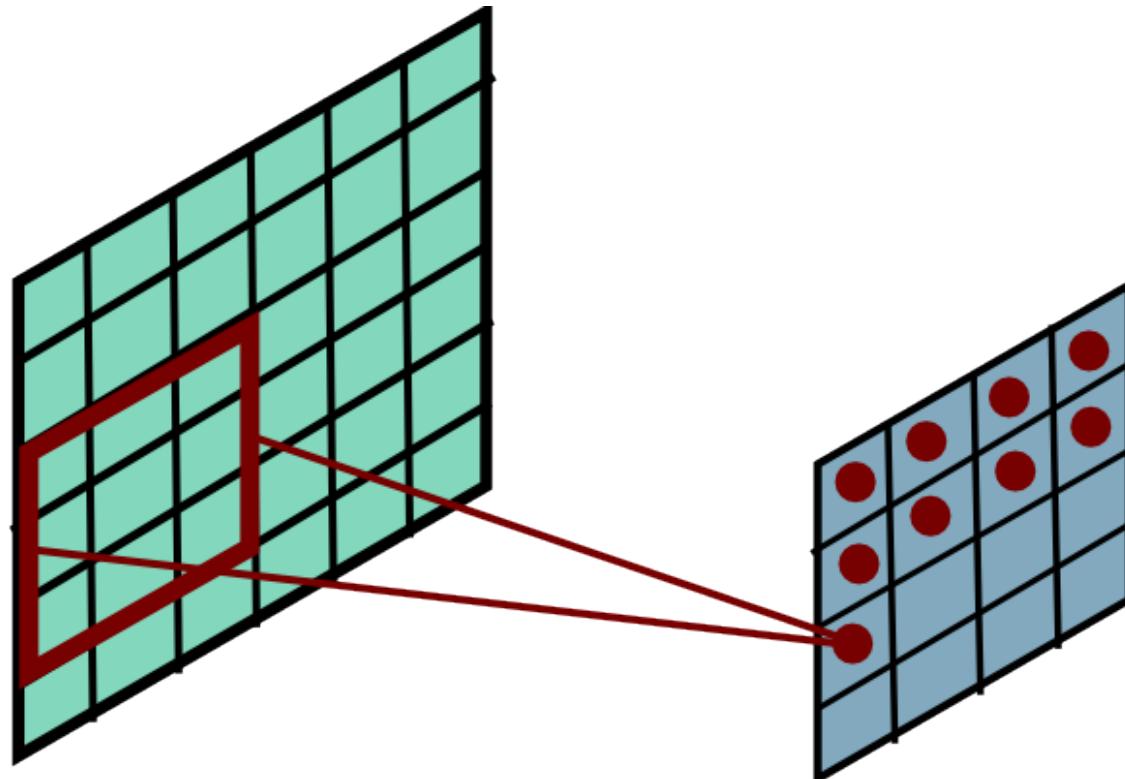
Convolutional Layer



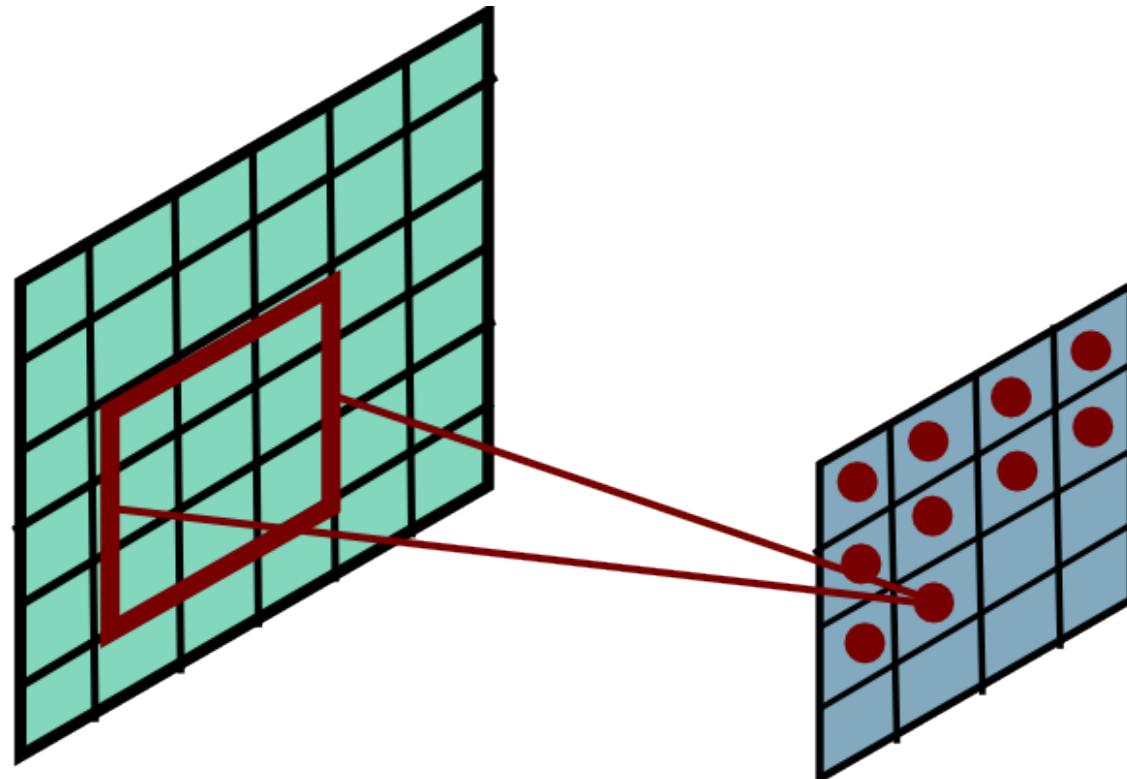
Convolutional Layer



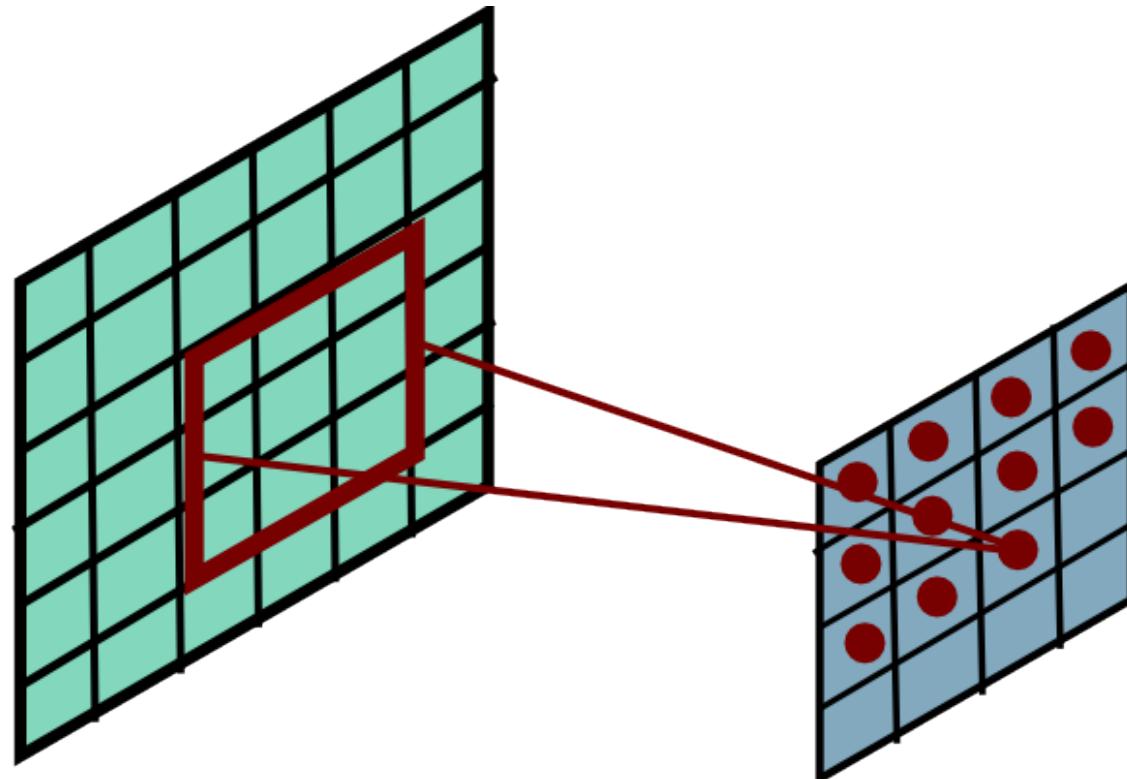
Convolutional Layer



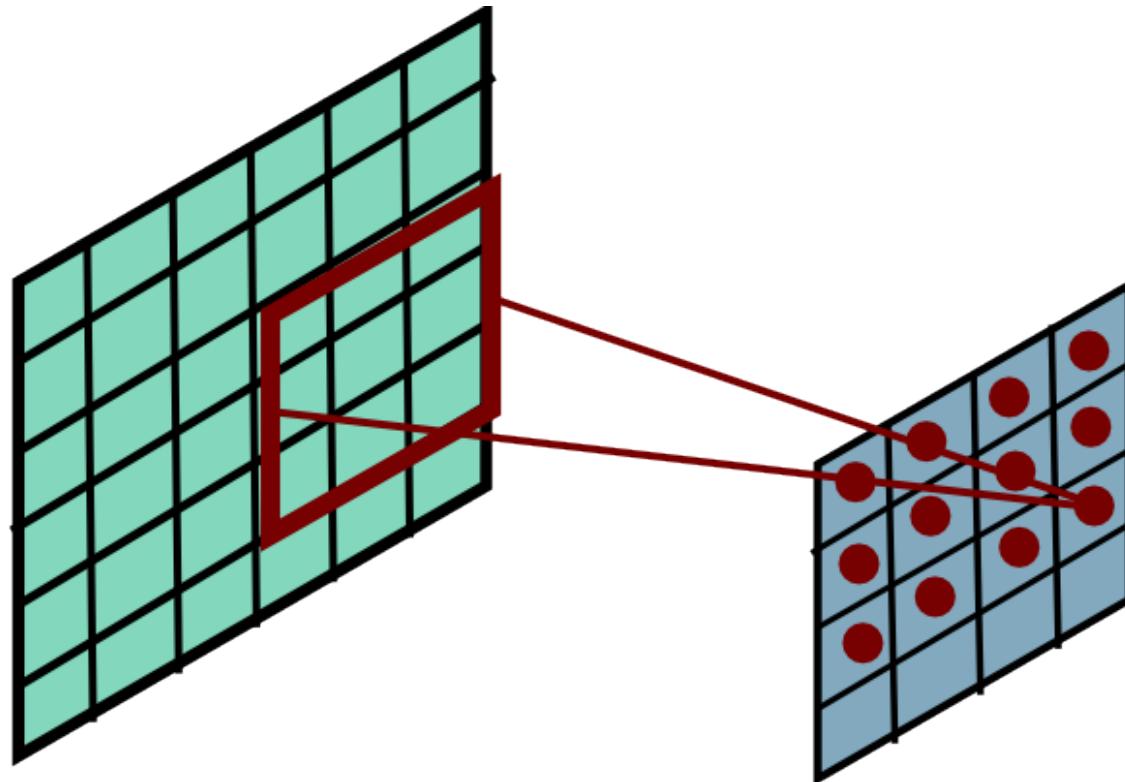
Convolutional Layer



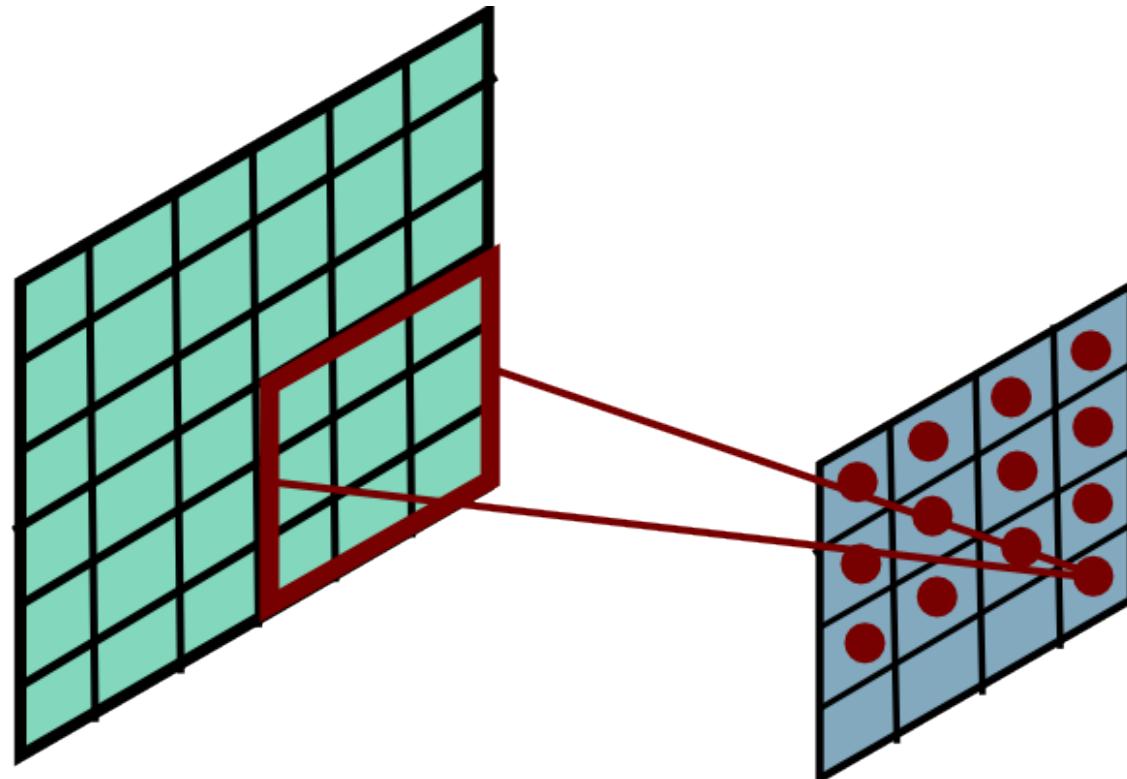
Convolutional Layer



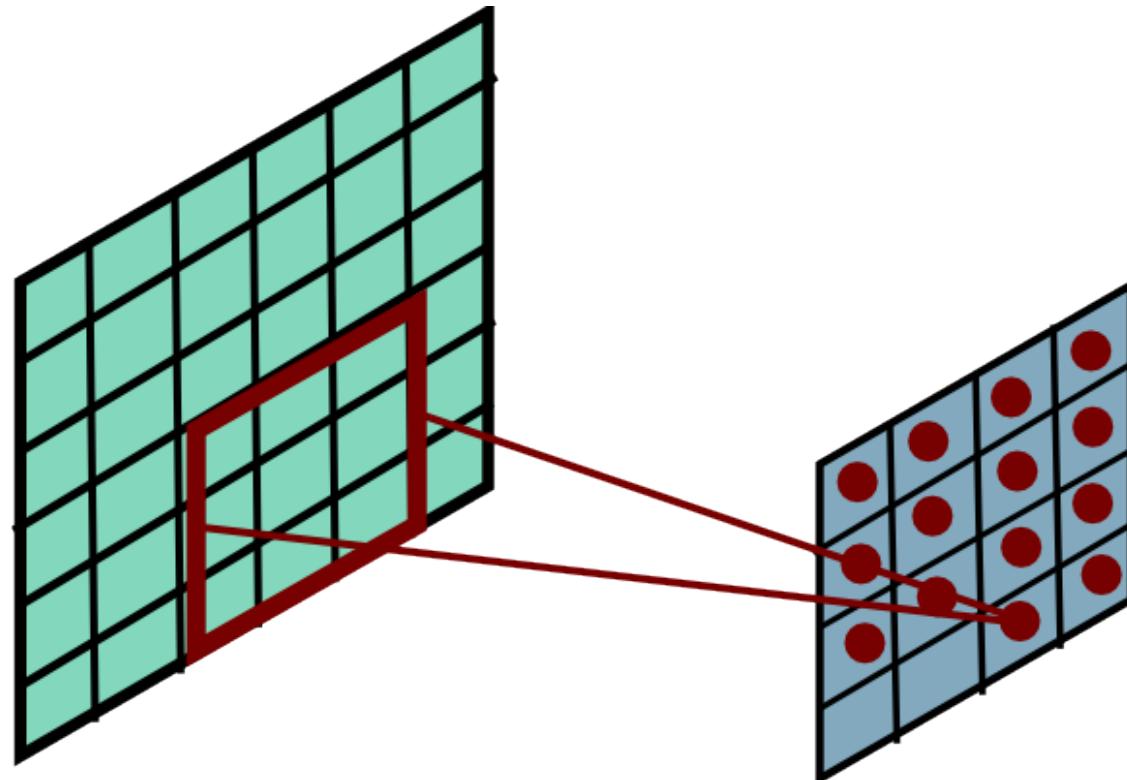
Convolutional Layer



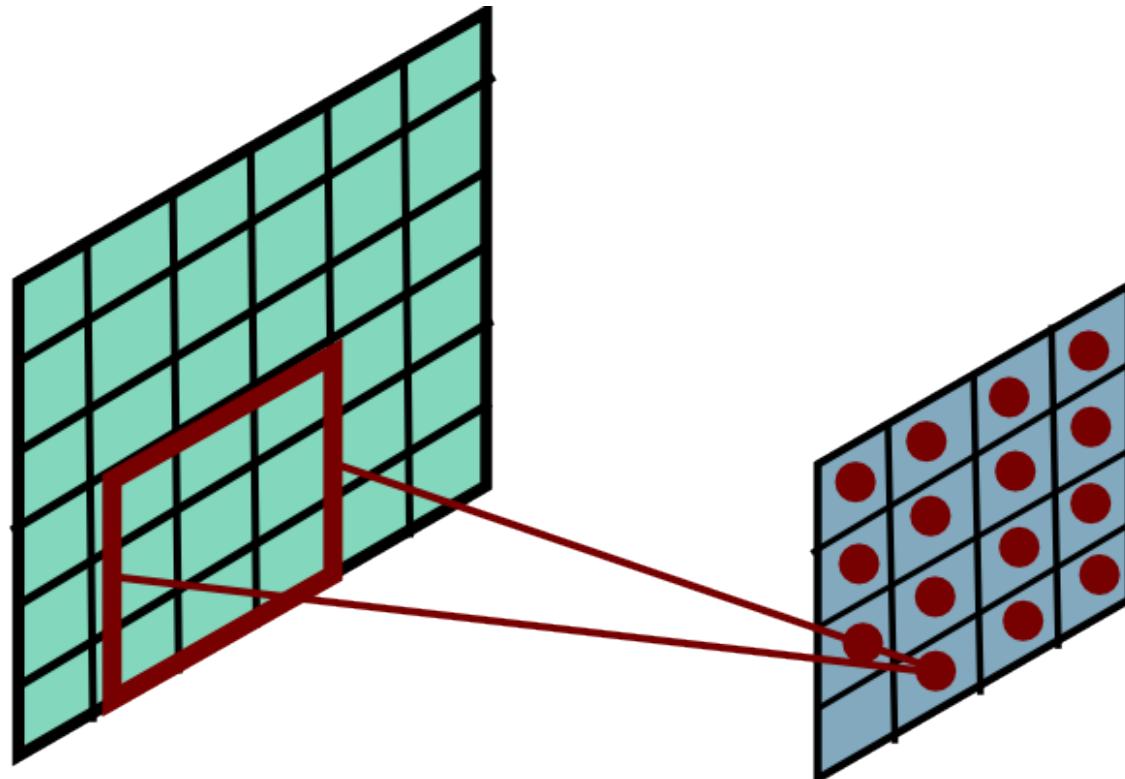
Convolutional Layer



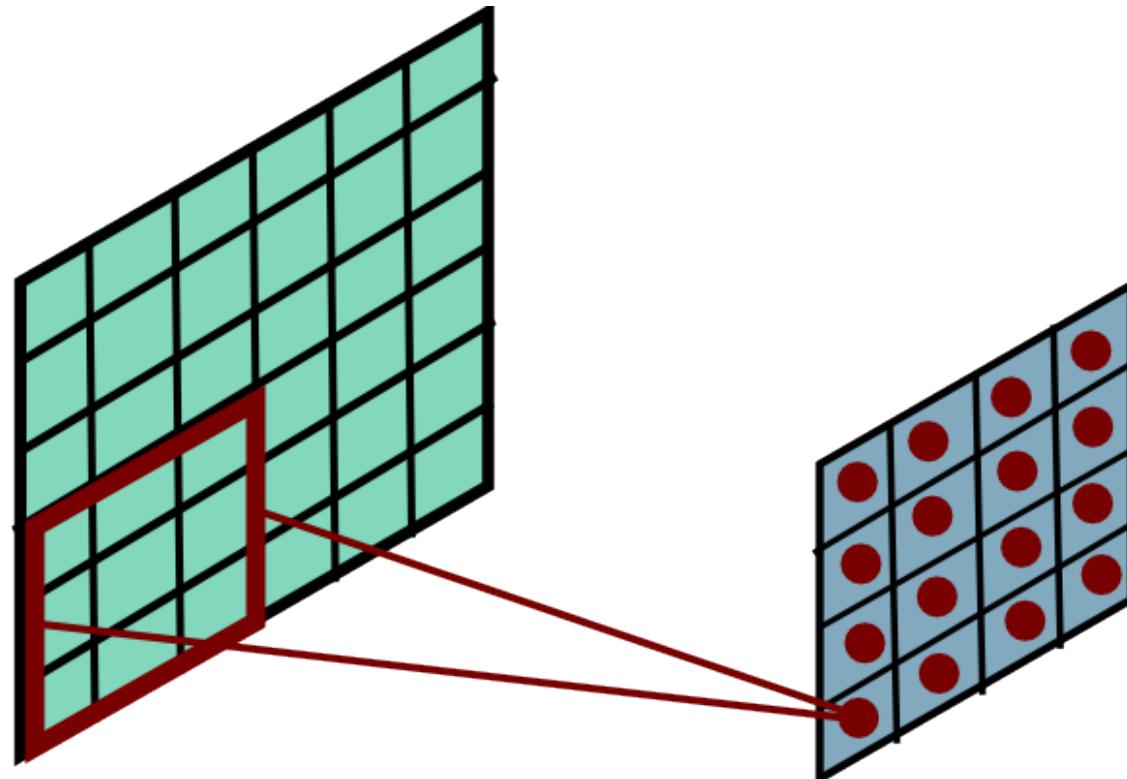
Convolutional Layer



Convolutional Layer



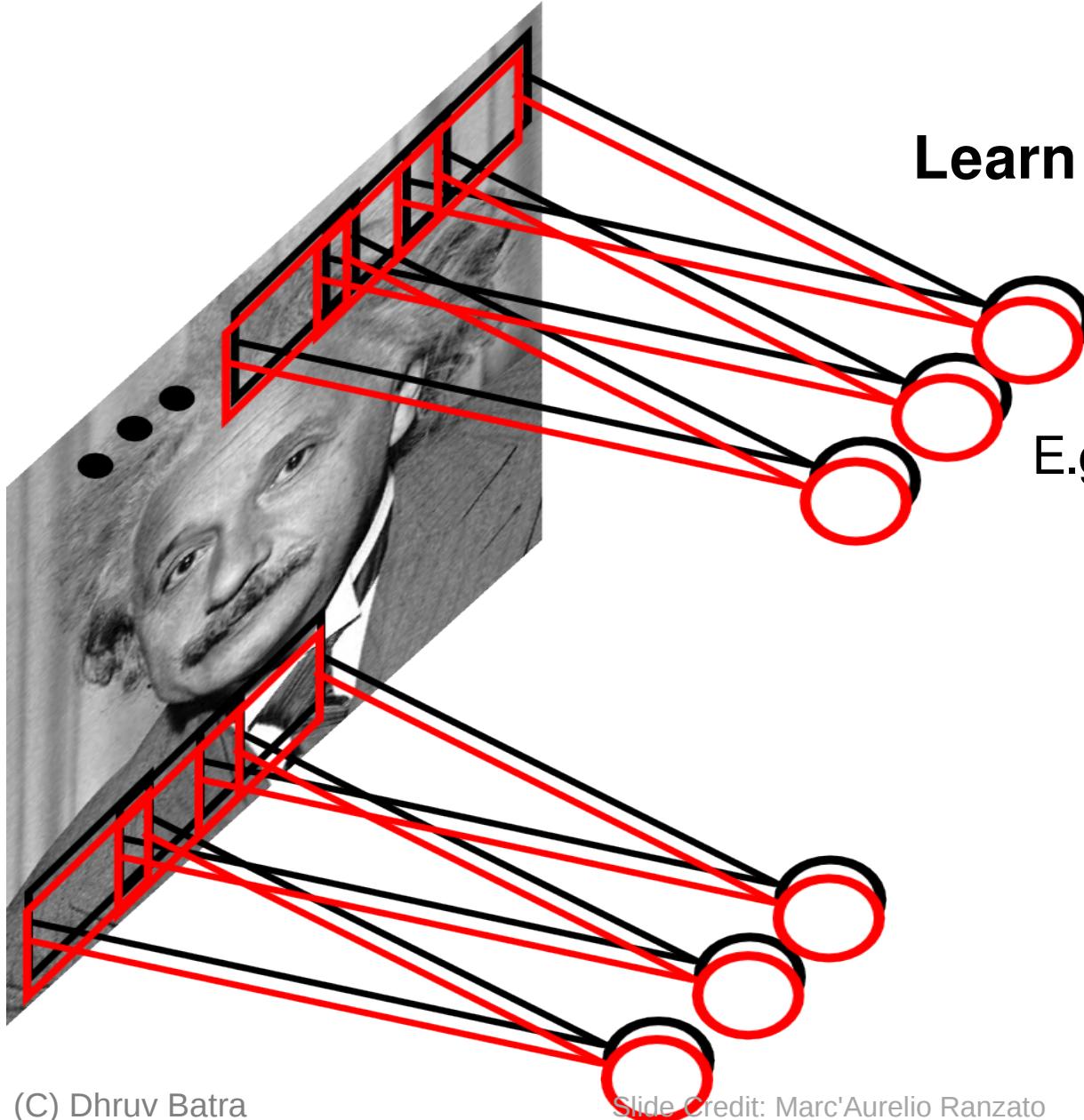
Convolutional Layer



Convolution Explained

- <http://setosa.io/ev/image-kernels/>
- <https://github.com/bruckner/deepViz>

Convolutional Layer



Learn multiple filters.

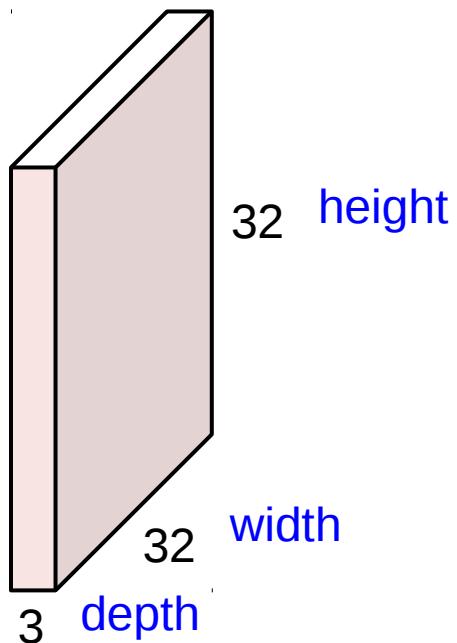
E.g.: 200x200 image
100 Filters
Filter size: 10x10
10K parameters

FC vs Conv Layer

FC vs Conv Layer

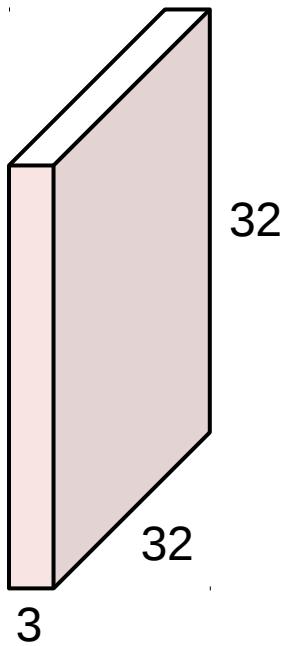
Convolution Layer

32x32x3 image



Convolution Layer

32x32x3 image



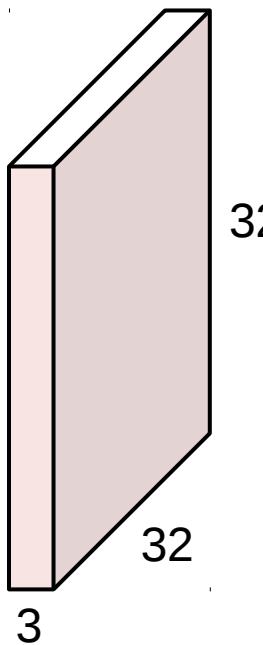
5x5x3 filter



Convolve the filter with the image
i.e. “slide over the image spatially,
computing dot products”

Convolution Layer

32x32x3 image



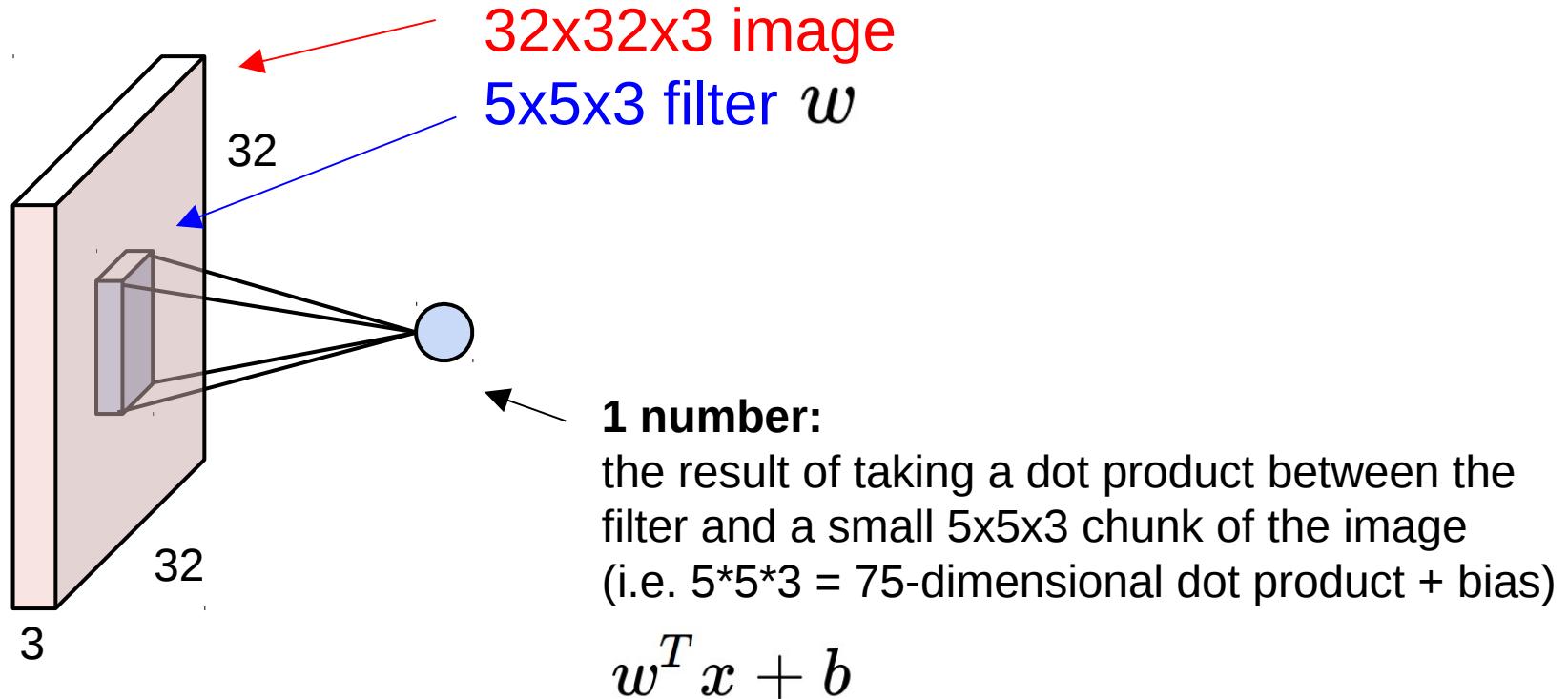
5x5x3 filter



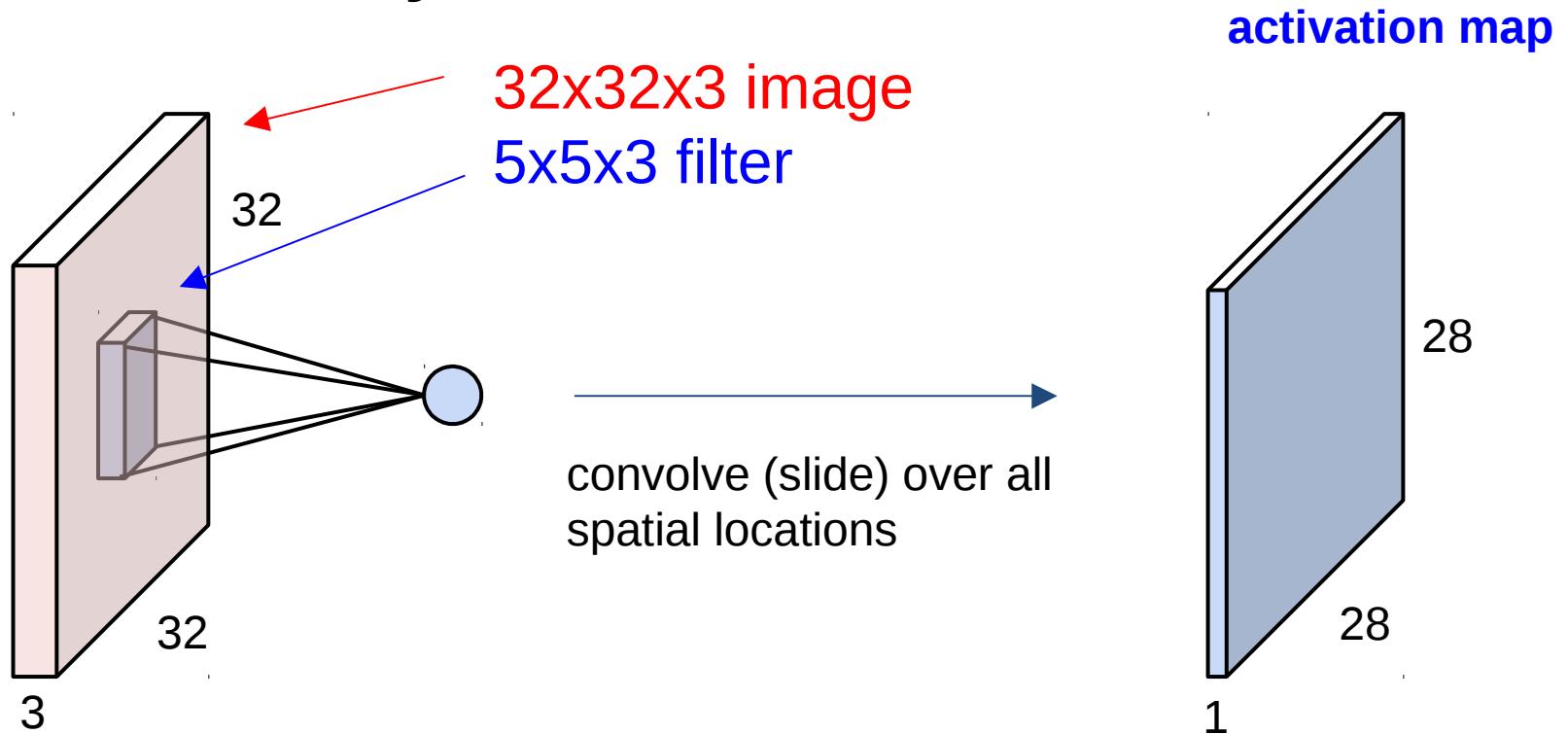
Filters always extend the full depth of the input volume

Convolve the filter with the image
i.e. “slide over the image spatially,
computing dot products”

Convolution Layer

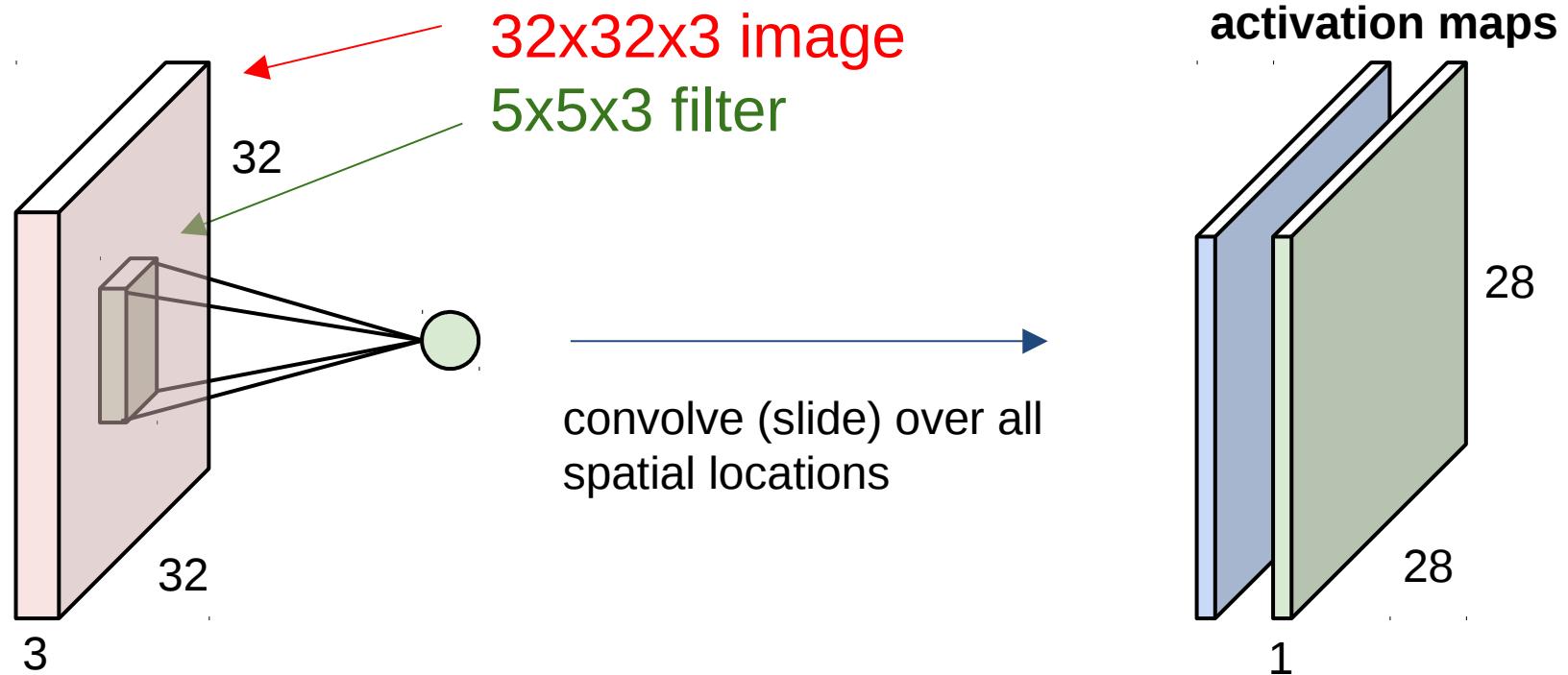


Convolution Layer

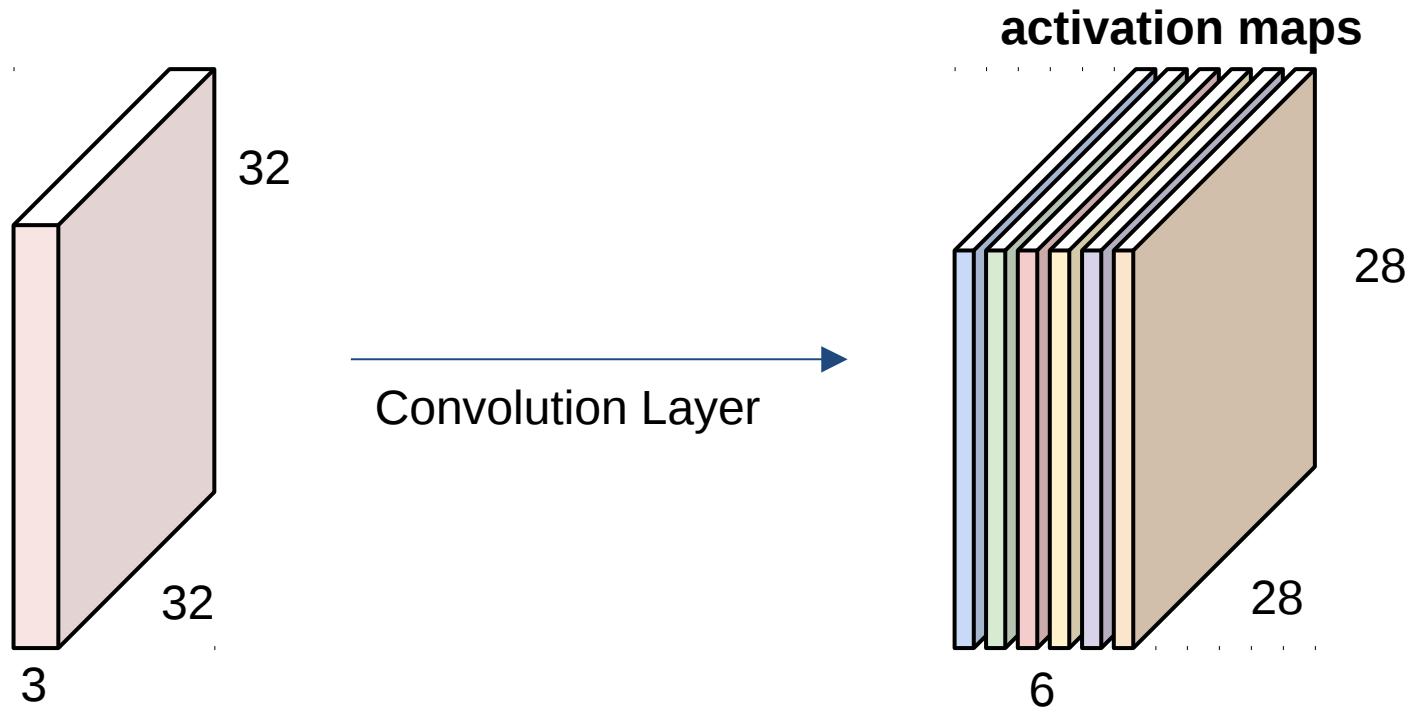


Convolution Layer

consider a second, green filter

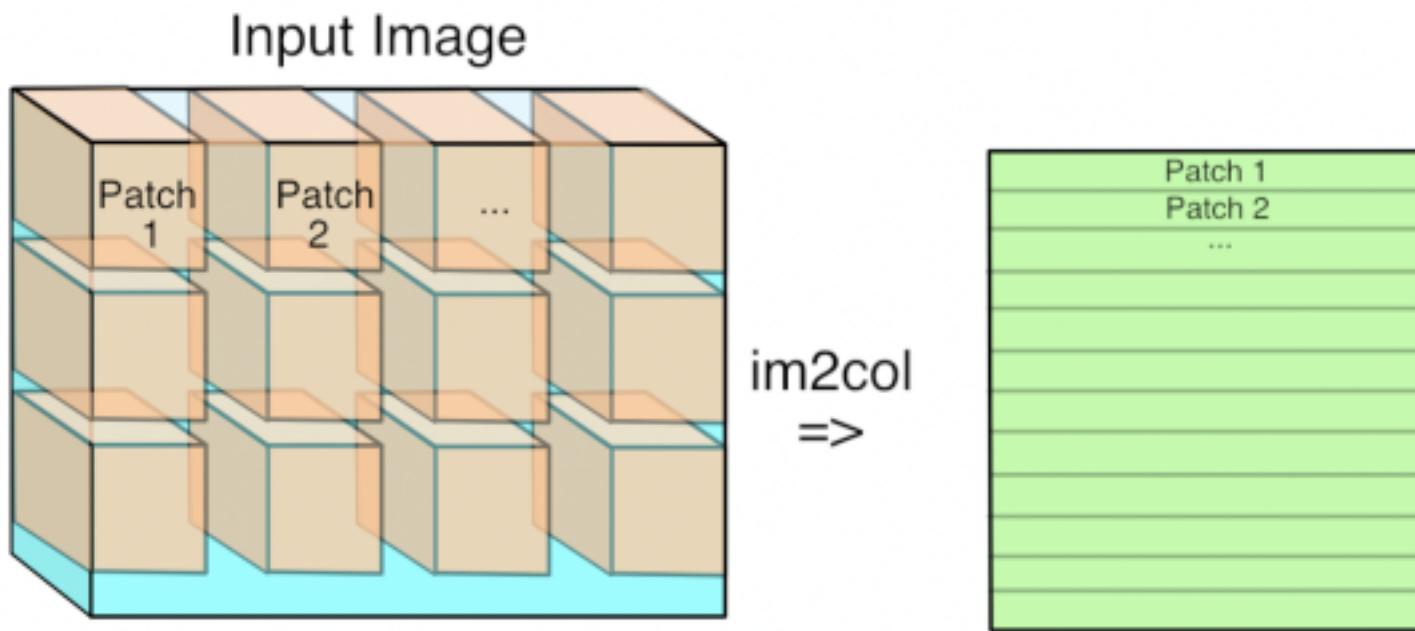


For example, if we had 6 5x5 filters, we'll get 6 separate activation maps:

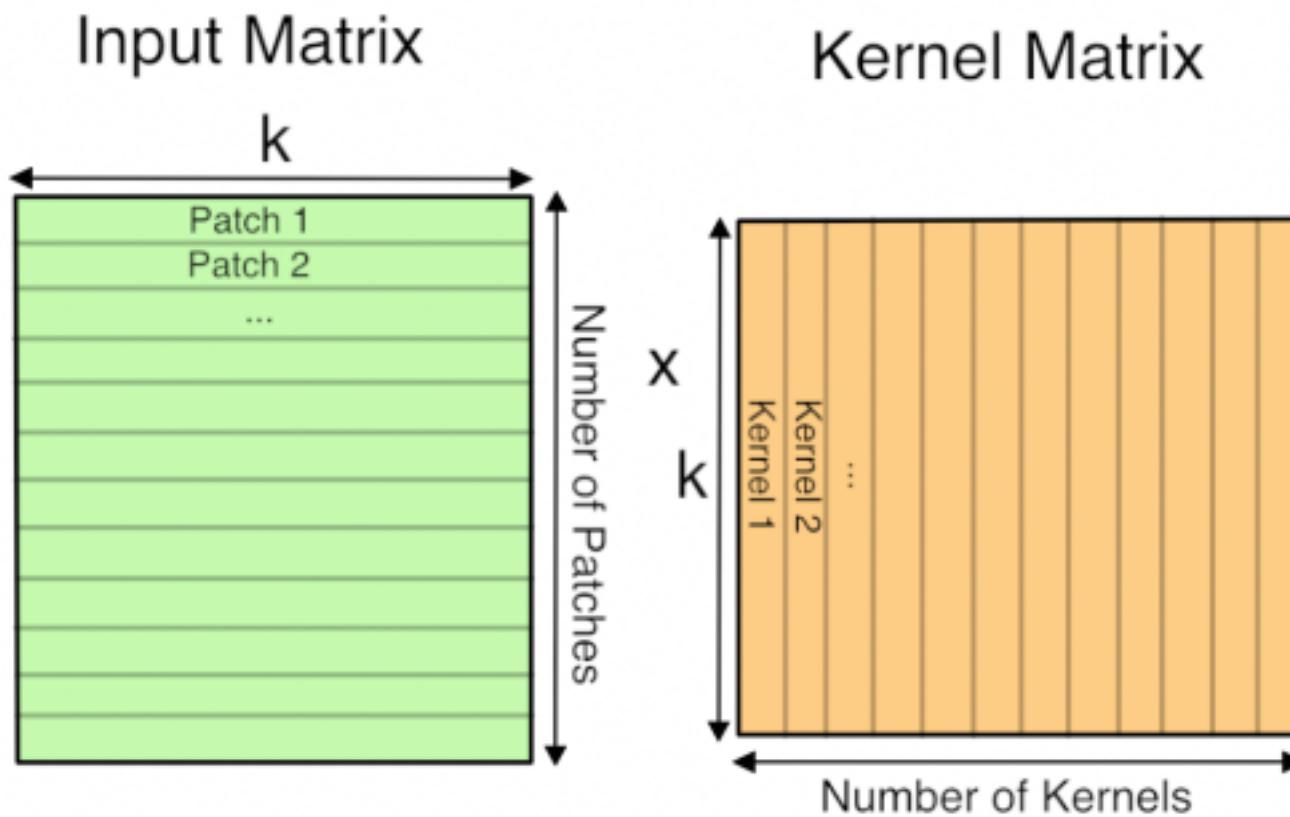


We stack these up to get a “new image” of size 28x28x6!

Im2Col

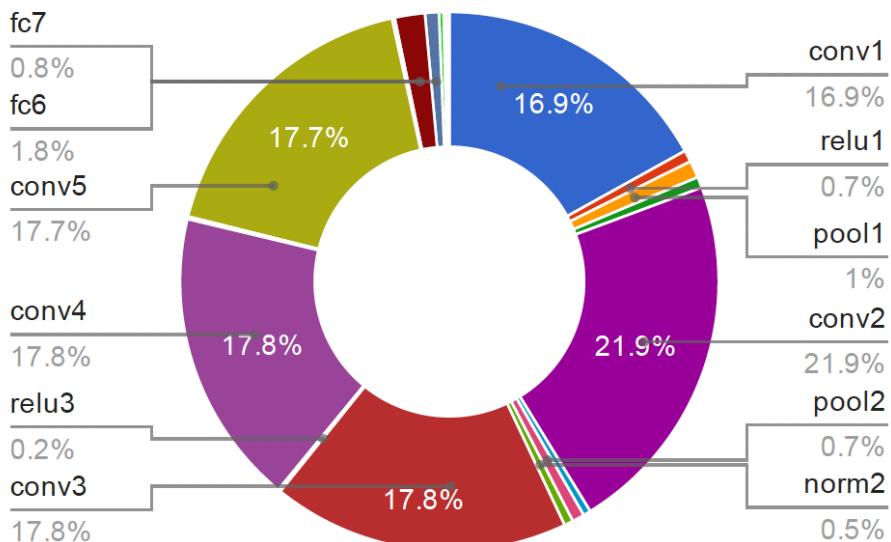


GEMM

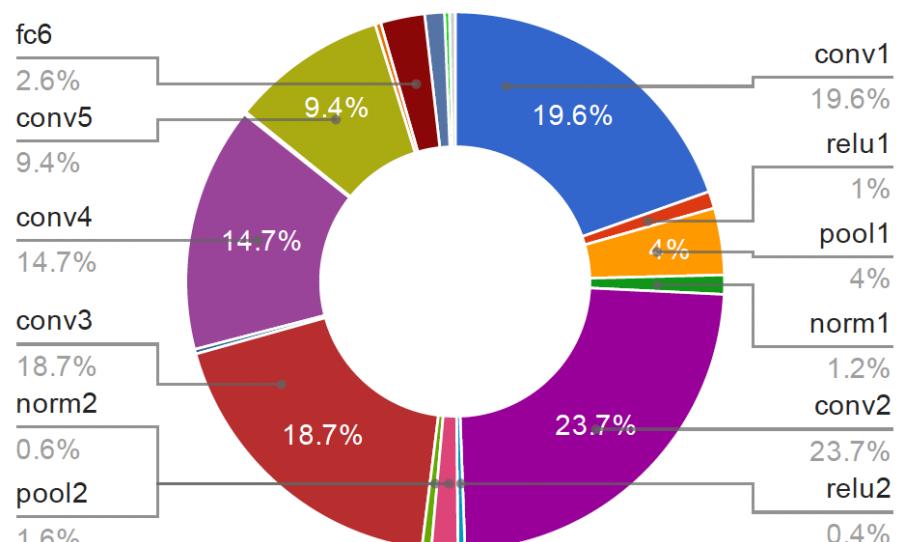


Time Distribution of AlexNet

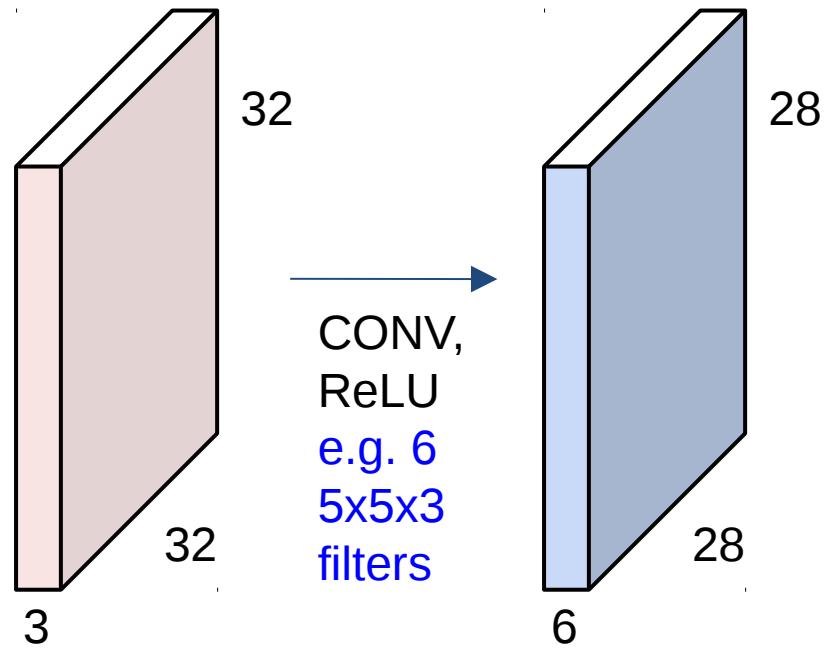
GPU Forward Time Distribution



CPU Forward Time Distribution



Preview: ConvNet is a sequence of Convolution Layers, interspersed with activation functions



Preview: ConvNet is a sequence of Convolutional Layers, interspersed with activation functions

