

CS 2316

Pair Homework 6 – Box Packer

Due: Friday, March 2nd, 2012 before 11:55 PM

Out of 100 points

Files to submit: 1. HW6.py

This is a PAIR PROGRAMMING Assignment: Work with your assigned partner!

For pair programming assignments, you and your partner should turn in identical assignments. List both partners names at the top. Your submission must not be substantially similar to another pairs' submission. Collaboration at a reasonable level will not result in substantially similar code. Students may only collaborate with fellow students currently taking CS 2316, the TA's and the lecturer. Collaboration means talking through problems, assisting with debugging, explaining a concept, etc. You should not exchange code or write code for others.

For Help:

- TA Helpdesk – Schedule posted on class website.
- Email TA's or use T-Square Forums

Notes:

- **Don't forget to include the required comments and collaboration statement (as outlined on the course syllabus).**
 - *Do not wait until the last minute to do this assignment in case you run into problems.*
 - **Read the entire specifications document before starting this assignment.**
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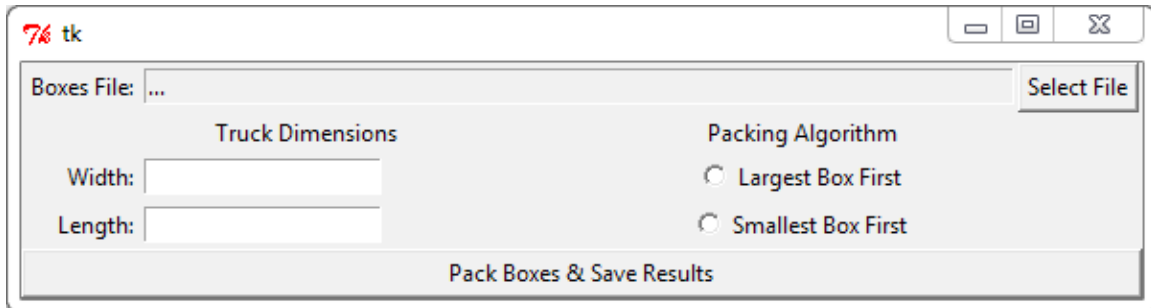
Premise

This homework will have you packing rectangular objects into a 2D space, similar to packing boxes into a flat truck. You will be given the dimensions of the space you are packing objects into, as well as a list of boxes. With this information, you will implement and analyze two algorithms that will pack the boxes into the truck: the first which packs the largest boxes into the truck first, and the second which packs the smallest boxes into the truck first. Your program will then report to the user how many boxes were packed, which boxes were packed, which boxes were not packed, and how much space on the truck is left unfilled, using a GUI that you will create.

Homework 6 is a problem-solving homework; we want you to reason through how to develop the algorithms and place things in the GUI, so **do not wait until the last minute to start this assignment**, as this assignment requires you to implement a large amount of

Method Name: **__init__**

This method is automatically called whenever you create a new instance of your GUI class. The `__init__` method is responsible for arranging and initializing your GUI. You should create a GUI which looks like the following:

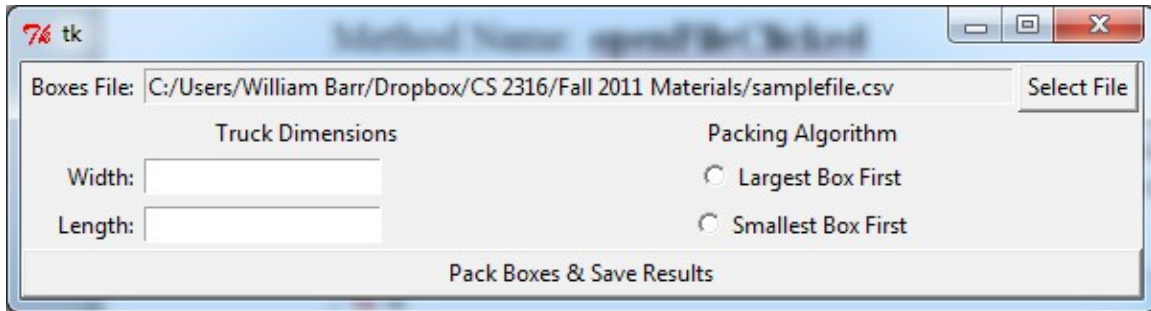


You may generate this window however you wish, but it is *highly* suggested that you use the grid layout manager. Things to note about the GUI you see:

- The entry box between the “Boxes File:” label and the “Select File” button is width 75, readonly, and has text “...” if no file has been selected.
- Clicking on the “Select File” button should call the `openFileClicked` method.
- Largest Box First and Smallest Box First are Radiobutton widgets. When the window is first opened, neither of these radio buttons should be selected.
- The width and length entry boxes are the default width and have a state of `NORMAL`.
- The “Pack Boxes & Save Results” button should span the width of the entire window (Hint: To make something like a button or entry box expand to take up the whole space, sticky it in both the east and west directions when gridding). Clicking on this button calls the `packNSaveClicked` method.

Method Name: **openFileClicked**

This method will simply launch a file open dialog box and prompt the user to select a file. If the user selects a file, the text for the Entry box beside the “Boxes file:” label will be set to the file the user chose. If the user chooses cancel, you must set the text of this entry box to be “...”.



Method Name: **readBoxesFile**

Parameters:

None

Return Value:

None

Description:

This method will open the file which the user specified in the open file dialog box, read in the CSV file, and store the data that is read from the file as an instance variable which points to a list of lists. As you read in each row from the CSV file, you should convert the width and length data into integers before saving the row.

In the event that a piece of data in the CSV file is malformed (doesn't have all the required data or has a non-integer width and/or length) or the user did not give you a valid CSV file, you should raise a `ValueError` which you will catch in the `packAndSaveResults` method.

Remember to close the file when you are finished.

Method Name: **isValidLocation**

Parameters:

- Integer – The row number of the cell you're testing
- Integer – The column number of the cell you're testing
- Integer – The width of the box you're trying to pack
- Integer – The length of the box you're trying to pack

Return Value:

Boolean – True if the box can be packed into the truck starting at location row, col, False if it cannot be packed starting at that location.

Description:

This method will check to see if you can pack a box (with certain dimensions that you passed in) into the truck, with the box's upper left corner starting at the row, column position that was passed in. Do not change the orientation of the box when trying to check and see if the location is valid. (Your union does not allow you to rotate boxes!)

The method should return True if none of the cells in the truck that would be occupied by the box are used by another box, and if the box can fit into the truck at that location (i.e. doesn't extend beyond the boundaries of the truck). This method should return False if there is any overlap or if the box would extend beyond the boundaries of the truck.

Method Name: **fillTruckLocation()**

Parameters:

Integer – The row of the space where you wish to start packing the box.

Integer – The column of the space where you wish to start packing the box.

List – The list of box information

Return Value:

None

Description:

This method will accept a row and column, which represents the location where the upper left corner of the box will be located. You must fill in spaces starting at row, col and expanding to the right the width of the box and expanding down the length of the box. You should fill in each cell with the Box ID of the box you are filling the space with.

Method Name: **packBox()**

Parameters:

List – A list containing the data for one particular box.

Return Value:

A Boolean – True if the box was successfully packed into the truck, False if it was not.

Description:

This method will look through the truck and try to find the first empty cell, starting with the first row and first column, then moving to the right on that row until there are no more cells to check, then moving to the second row, first column, then moving to the right until there are no more cells to check on that row, and so on and so forth.

When you find an empty cell, you will attempt to pack the upper left-corner of the box into this position, and the rest of the box will extend to the right and down; use the isValidLocation method you wrote to see if the box will fit in this location. If it will fit, call the fillTruckLocation method with the appropriate information and return True. If the box will not fit into this location, continue searching for an empty cell until you find another one. Repeat this process of finding empty cells and checking to see if the box will fit at that location until you either find a location where the box will fit or you run out of empty locations in the truck. If you have checked all of the empty locations in the

truck and none are valid, or if there are no empty locations left, you should return False.

Method Name: **packTruck()**

Parameters:

None

Return Value:

A List – A list of all boxes from the CSV file that were not packed into the truck with the given algorithm.

Description:

This method will attempt to pack all the boxes from the CSV file into the truck. The order in which it will attempt to place boxes into the truck is dependent upon which radio button the user selected; if the user picked “Largest Box First”, you will attempt to pack the boxes such that the box with the largest area is packed on the truck first, followed by the second largest area, etc. If the user picked “Smallest Box First”, you will attempt to pack the boxes such that the box with the smallest area is packed on the truck first, followed by the second smallest area, etc.

When you have attempted to pack all the boxes, you should return a list of boxes that were not packed into the truck.

Method Name: **writeTruckToCSV()**

Parameters:

None

Return Value:

None

Description:

This method will write out the contents of the truck as a CSV file. You should be able to open this CSV file in a program such as Excel or LibreOffice Calc and see the “table” view of the boxes packed into your truck. You do not need to format the data in any special way before writing it out. You should save this file as “truckview.csv”.

Use of csv.writer will make this method trivial to implement. Remember to close the file when you are finished.

Function Name: **packNSaveClicked**

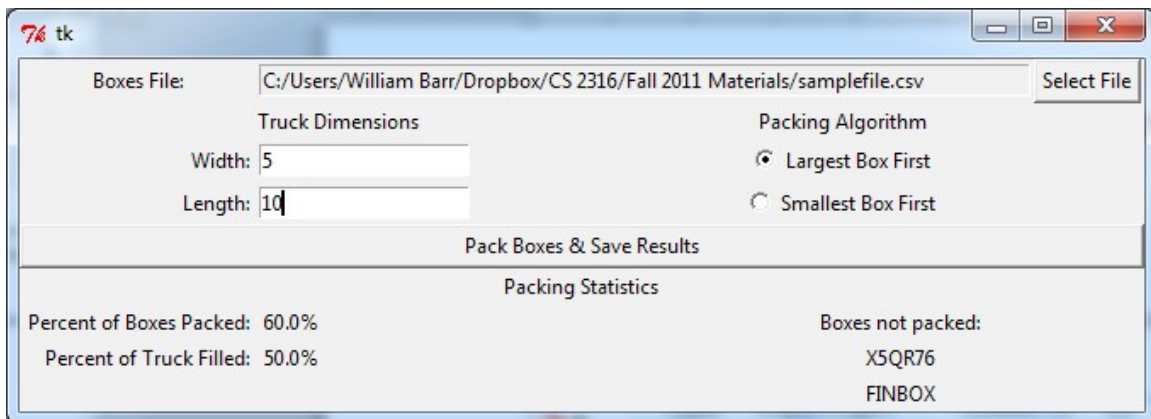
This function will set up the truck to have the appropriate number of empty spaces, read in the file containing information about the boxes, pack the boxes using the algorithm the user specified, write the contents of the truck out to the “truckview.csv” file, and add some widgets to the GUI to show the user some statistics about the truck they just packed.

First, you must make sure that the user has entered an appropriate width and

length for the truck as well as selected a packing algorithm. If the user did not provide all of this information (or the user entered an invalid value for width or length), you should pop up a message dialog box informing the user of the mistake.

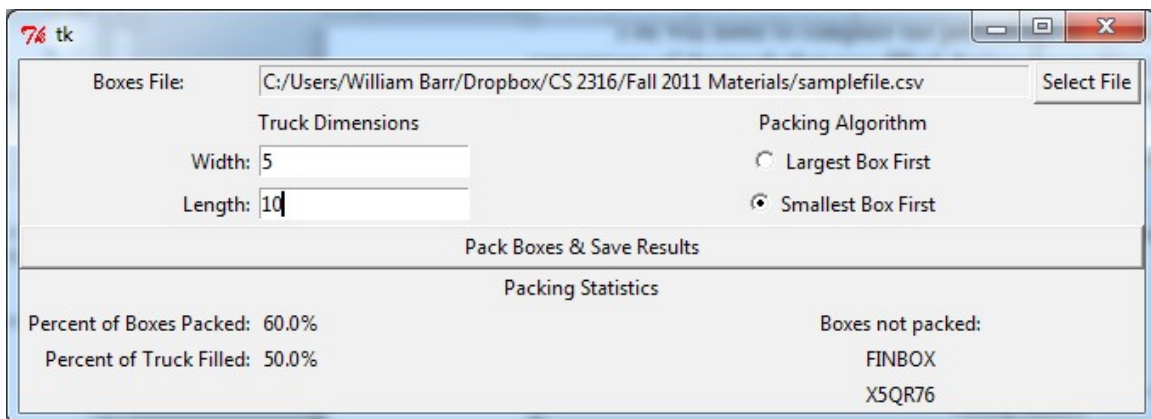
If `readBoxesFile` raises a `ValueError` when you call it, you should display a message dialog box to the user informing them that the CSV file is invalid. You should not attempt to pack any boxes if this occurs.

When you have successfully packed as many boxes as possible using the user's specified algorithm, you should update the GUI so that it looks like the following:



You will need to compute the percentage of the boxes packed as well as the percentage of the truck that was filled during the packing process. Additionally, you will need to display the Box IDs of all boxes that were not packed.

Below is another test-case output so you can validate your program:



Extra Credit Opportunity:

If you examine the algorithm and packing procedure we described above, you will notice that this is a rather naïve way to pack the truck. Sometimes, if we had changed the order in which we packed boxes, or didn't necessarily always pack

the largest or smallest box, we could find a more optimal solution. Also, we did not permit any kind of transformation of the box, such as a rotation. In some cases, rotating the box would permit the box to be packed.

For extra credit, come up with your own packing algorithm and method to fill in spaces in the truck; there are no restrictions on what you can do to pack the boxes this time around. Your objective is maximize the percentage of boxes packed, the percentage of the truck that is filled, or (optimally) both! The TAs will award extra credit based on the creativity of the approach as well as the results; the better your algorithm is at maximizing the number of boxes packed or the amount of the truck filled, the more extra credit you will receive. Make sure that the basics of your program work correctly; if your extra credit attempt breaks the base functionality, you will lose points!

If you choose to do this, you need to modify your program so you have three radio buttons instead of two; the third radio button should be labeled appropriately, and when a user selects it, it should pack the boxes using your packing algorithm and method. At the top of your file, write a brief description of how your algorithm and method work and why it is better than the two algorithms we provided.

Be sure to comment your custom algorithm thoroughly!

Grading:

You will earn points as follows for each piece of functionality that works correctly according to the specifications.

The GUI		20
GUI has all required initial components	10	
openFileClicked works as described	5	
GUI has proper error checking	5	
readBoxesFile()		6
Successfully reads in all information from file	2	
Stores data from file in an instance variable	2	
Converts width and length into integers	2	
isValidLocation()		10
Checks truck boundaries	5	
Correctly checks all relevant spaces in truck	5	
fillTruckLocation()		7
Correctly fills all spaces in the truck with given dimensions	7	
packBox()		8
Correctly searches for empty spaces	5	
Correctly calls fillTruckLocation when space found	3	
packTruck()		25
Keeps track of unpacked boxes correctly	10	
Attempts to execute correct packing algorithm	5	
Packs boxes in correct order	10	
writeCSVFile()		4
Writes CSV file correctly	4	
packNSaveClicked()		20
Adds new GUI elements after computation	10	
Does not reimplement functionality from other methods	3	
Percent packed and percent empty computed correctly	7	